

# TJA1081G

## FlexRay node transceiver

Rev. 1 — 28 October 2016

Product data sheet

## 1. General description

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The TJA1081G is a FlexRay transceiver that is fully compliant with FlexRay electrical physical layer specification ISO 17458-4:2013 (see [Ref. 1](#) and [Ref. 2](#)). It is intended for communication systems from 2.5 Mbit/s to 10 Mbit/s and provides an advanced interface between the protocol controller and the physical bus in a FlexRay network.

The TJA1081G features enhanced low-power modes, optimized for ECUs that are permanently connected to the battery.

The TJA1081G provides differential transmit capability to the network and differential receive capability to the FlexRay controller. It offers excellent EMC performance as well as effective ESD protection.

The TJA1081G actively monitors system performance using dedicated error and status information (that any microcontroller can read), along with internal voltage and temperature monitoring.

The TJA1081G supports mode control as used in the TJA1080A (see [Ref. 3](#)) and is fully functionally and pin compatible with the TJA1081B (see [Ref. 4](#)).

## 2. Features and benefits

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### 2.1 Optimized for time triggered communication systems

- Compliant with ISO 17458-4:2013 (see [Ref. 2](#))
- Automotive product qualification in accordance with AEC-Q100
- Data transfer rates from 2.5 Mbit/s to 10 Mbit/s
- Very low ElectroMagnetic Emissions (EME) to support unshielded cable, meeting latest industry standards
- Differential receiver with wide common-mode range for high ElectroMagnetic Immunity (EMI), meeting latest industry standards
- Enhanced EMC performance compared with TJA1081B
- Auto I/O level adaptation to host controller supply voltage  $V_{IO}$
- Can be used in 14 V, 24 V and 48 V powered systems
- Instant transmitter shut-down interface (via BGE pin)
- Independent power supply ramp-up for  $V_{BAT}$ ,  $V_{CC}$  and  $V_{IO}$

### 2.2 Low-power management

- Low-power management including inhibit switch
- Very low current in Sleep and Standby modes



- $V_{BAT}$  operating range: 4.75 V to 60 V
- Gap-free specification
- Local and remote wake-up
- Supports remote wake-up via dedicated data frames
- Wake-up source recognition

### 2.3 Diagnosis (detection and signaling)

- Enhanced supply monitoring of  $V_{BAT}$ ,  $V_{CC}$  and  $V_{IO}$
- Overtemperature detection
- Short-circuit detection on bus lines
- $V_{BAT}$  power-on flag (first battery connection and cold start)
- Clamping diagnosis on pin TXEN
- BGE status feedback

### 2.4 Protection

- Bus pins protected against  $\pm 6$  kV ESD pulses according to IEC 61000-4-2 and HBM
- Pins  $V_{BAT}$  and WAKE protected against  $\pm 6$  kV ESD pulses according to IEC 61000-4-2
- Bus pins protected against transients in automotive environment (according to ISO 7637 class C)
- Bus pins short-circuit proof to battery voltage (14 V, 24 V and 48 V) and ground
- Fail-silent behavior in the event of an undervoltage on pins  $V_{BAT}$ ,  $V_{CC}$  or  $V_{IO}$
- Passive behavior of bus lines while the transceiver is not powered
- No reverse currents from the digital input pins to  $V_{IO}$  or  $V_{CC}$  when the transceiver is not powered

### 2.5 Functional classes according to FlexRay electrical physical layer specification (see [Ref. 2](#))

- Bus driver voltage regulator control
- Bus driver - bus guardian interface
- Bus driver logic level adaptation
- Bus driver remote wake-up

### 3. Quick reference data

Table 1. Quick reference data

| Symbol          | Parameter                                       | Conditions  | Min  | Typ | Max   | Unit    |
|-----------------|---|---|------|-----|-------|---------|
| $V_{CC}$        | supply voltage                                  |   | 4.75 | -   | 5.25  | V       |
| $V_{uvd(VCC)}$  | undervoltage detection voltage on pin $V_{CC}$  |   | 4.45 | -   | 4.72  | V       |
| $I_{CC}$        | supply current                                  | Normal mode; $V_{BGE} = V_{IO}$ ;<br>$V_{TXEN} = 0$ V | -    | 37  | 50    | mA      |
| $V_{BAT}$       | battery supply voltage                          |   | 4.75 | -   | 60    | V       |
| $V_{uvd(VBAT)}$ | undervoltage detection voltage on pin $V_{BAT}$ |   | 4.45 | -   | 4.715 | V       |
| $I_{BAT}$       | battery supply current                          | low-power modes;<br>no load on pin INH                | -    | -   | 55    | $\mu$ A |
|                 |   | normal-power modes                                    | -    | -   | 1     | mA      |
| $V_{IO}$        | supply voltage on pin $V_{IO}$                  |   | 2.8  | -   | 5.25  | V       |
| $V_{uvd(VIO)}$  | undervoltage detection voltage on pin $V_{IO}$  |   | 2.55 | -   | 2.765 | V       |
| $I_{IO}$        | supply current on pin $V_{IO}$                  | Normal and Receive-only modes;<br>$V_{TXD} = V_{IO}$  | -    | -   | 1     | mA      |
| $V_{ESD}$       | electrostatic discharge voltage                 | IEC 61000-4-2 on pins BP and BM to ground             | -6   | -   | +6    | kV      |

### 4. Ordering information

Table 2. Ordering information

| Type number | Package |   | Version  |
|-------------|---------|---|----------|
|             | Name    | Description   |          |
| TJA1081GTS  | SSOP16  | SSOP16: plastic shrink small outline package; 16 leads; body width 5.3 mm | SOT338-1 |

5. Block diagram

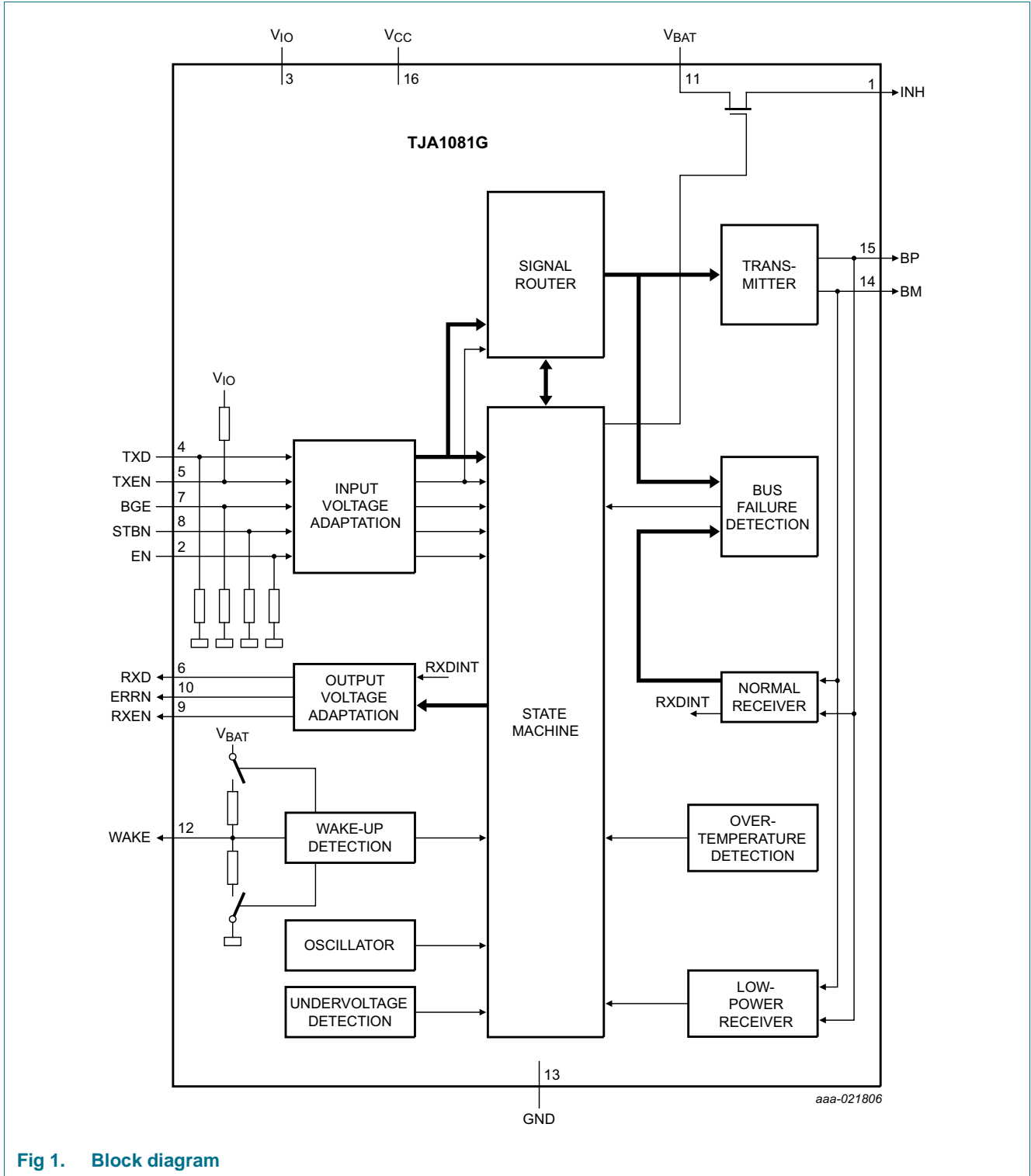


Fig 1. Block diagram

## 6. Pinning information

### 6.1 Pinning

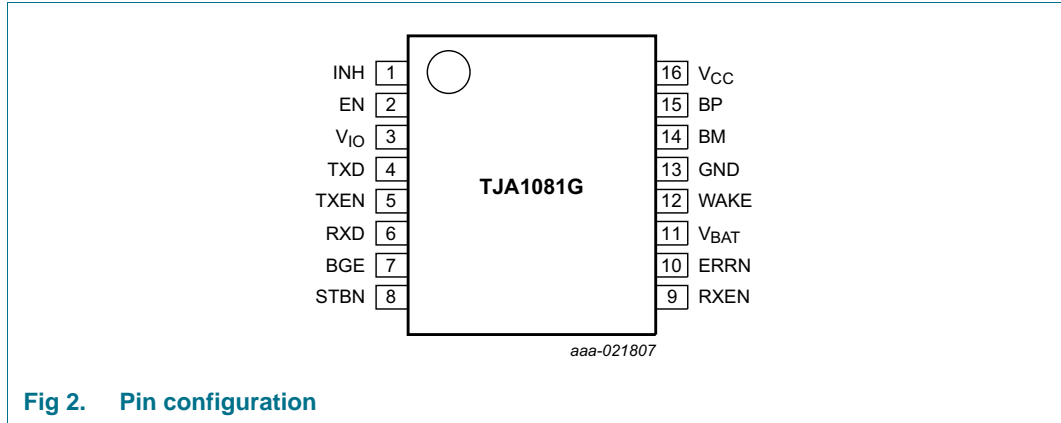


Fig 2. Pin configuration

### 6.2 Pin description

Table 3. Pin description

| Symbol           | Pin | Type <sup>[1]</sup> | Description   |
|------------------|-----|---------------------|---|
| INH              | 1   | AO                  | inhibit output for switching external voltage regulator                             |
| EN               | 2   | I                   | enable input; enabled when HIGH; internal pull-down                                 |
| V <sub>IO</sub>  | 3   | P                   | supply voltage for V <sub>IO</sub> voltage level adaptation                         |
| TXD              | 4   | I                   | transmit data input; internal pull-down   |
| TXEN             | 5   | I                   | transmitter enable input; when HIGH transmitter disabled; internal pull-up          |
| RXD              | 6   | O                   | receive data output   |
| BGE              | 7   | I                   | bus guardian enable input; when LOW transmitter disabled; internal pull-down        |
| STBN             | 8   | I                   | standby input; low-power mode when LOW; internal pull-down                          |
| RXEN             | 9   | O                   | receive data enable output; when LOW bus activity detected                          |
| ERRN             | 10  | O                   | error diagnoses output; when LOW error detected                                     |
| V <sub>BAT</sub> | 11  | P                   | battery supply voltage  |
| WAKE             | 12  | AI                  | local wake-up input; internal pull-up or pull-down (depends on voltage at pin WAKE) |
| GND              | 13  | G                   | ground  |
| BM               | 14  | AIO                 | bus line minus  |
| BP               | 15  | AIO                 | bus line plus   |
| V <sub>CC</sub>  | 16  | P                   | supply voltage (+5 V)   |

[1] AO: analog output; AI: analog input; I: digital input (V<sub>IO</sub> related); O: digital output (V<sub>IO</sub> related); I/O: digital input/output (V<sub>IO</sub> related); AIO: analog input/output; P: power supply; G: ground.

## 7. Functional description

The block diagram of the transceiver is shown in [Figure 1](#).

### 7.1 Operating modes

The TJA1081G supports the following operating modes:

- Normal (normal-power mode)
- Receive-only (normal-power mode)
- Standby (low-power mode)
- Go-to-sleep (low-power mode)
- Sleep (low-power mode)
- PowerOff

#### 7.1.1 Bus activity and idle detection

The following mechanisms for activity and idle detection are valid in normal power modes:

- If the absolute differential voltage on the bus lines is higher than  $|V_{i(dif)det(act)}|$  for  $t_{det(act)(bus)}$ , activity is detected on the bus lines. Pin RXEN is switched LOW, releasing pin RXD:
  - if, after activity has been detected on the bus, the differential voltage on the bus lines is lower than  $V_{IL(dif)}$ , pin RXD will go LOW
  - if, after activity has been detected on the bus, the differential voltage on the bus lines is higher than  $V_{IH(dif)}$ , pin RXD will go HIGH
- If the absolute differential voltage on the bus lines is lower than  $|V_{i(dif)det(act)}|$  for  $t_{det(idle)(bus)}$ , idle is detected on the bus lines. Pin RXEN is switched HIGH, blocking pin RXD (which is switched HIGH or remains HIGH)

7.1.2 Signaling on pin ERRN

Pin ERRN provides either error information or wake-up information. The behavior of ERRN is determined by the host (via pins STBN and EN) and not by the operating mode.

If STBN is LOW, pin ERRN is configured to signal a wake-up event. When STBN and EN are both HIGH, pin ERRN is configured to provide an error alert. Signaling on pin ERRN is described in [Table 4](#).

If pin ERRN goes LOW in Standby mode or Sleep mode to signal a wake-up event, the host can switch the TJA1081G to Receive only mode (STBN → H) to determine if the wake-up is local or remote. A LOW level on ERRN in Receive only mode (provided the transition to Receive only mode was not triggered by EN going LOW in Normal mode) indicates a remote wake-up was detected. A HIGH level on ERRN signals a local wake-up.

If EN had been forced HIGH after an earlier wake-up event (to switch the TJA1081G to Normal mode), ERRN will always indicate the error detection status (in both Normal and Receive only modes).

Table 4. Signaling on pin ERRN

| STBN                                 | EN | Conditions   | ERRN |
|--------------------------------------|----|--|------|
| <b>Normal mode active</b>            |    |  |      |
| H                                    | H  | no error detected  | HIGH |
| H                                    | H  | error detected   | LOW  |
| <b>Receive only mode active</b>      |    |  |      |
| H                                    | L  | a wake-up was detected (ERRN went LOW in Standby/Sleep mode; EN was LOW) before the TJA1081G was switched to Receive only mode |      |
|                                      |    | local wake-up detected   | HIGH |
|                                      |    | remote wake-up detected  | LOW  |
| H                                    | L  | EN was forced HIGH previously in response to an earlier wake-up event before the transition to Receive only mode               |      |
|                                      |    | no error detected  | HIGH |
|                                      |    | error detected   | LOW  |
| <b>Standby or Sleep modes active</b> |    |  |      |
| L                                    | X  | no local or remote wake-up detected  | HIGH |
| L                                    | X  | local or remote wake-up detected   | LOW  |

ERRN is in a high-impedance state in PowerOff mode.

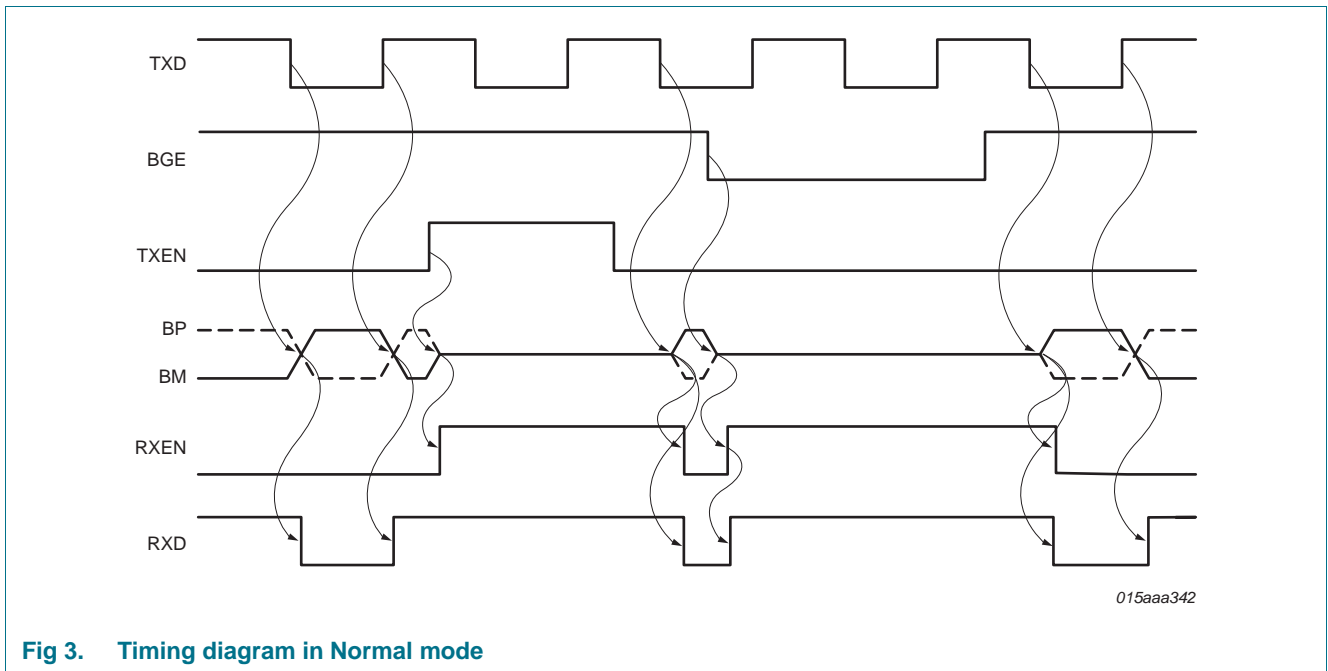
### 7.1.3 Signaling on pins RXEN and RXD

The TJA1081G operating mode determines signaling on pins RXEN and RXD, as detailed in [Table 5](#).

**Table 5. RXEN and RXD signaling**

| Operating mode | RXEN  |                                     | RXD   |                                     | Transmitter | INH      |
|----------------|---|-------------------------------------|---|-------------------------------------|-------------|----------|
|                | LOW   | HIGH                                | LOW   | HIGH                                |             |          |
| Normal         | bus active                                      | bus idle                            | DATA_0  | DATA_1 or idle                      | enabled     | HIGH     |
| Receive-only   |   |                                     |   |                                     | disabled    |          |
| Go-to-Sleep    | local or remote wake-up detected <sup>[1]</sup> | no local or remote wake-up detected | local or remote wake-up detected <sup>[1]</sup> | no local or remote wake-up detected |             | floating |
| Standby        |   |                                     |   |                                     |             |          |
| Sleep          |   |                                     |   |                                     |             |          |
| PowerOff       | high impedance                                  |                                     | HIGH  |                                     |             |          |

[1] Valid if V<sub>IO</sub> and (V<sub>CC</sub> or V<sub>BAT</sub>) are present.



**Fig 3. Timing diagram in Normal mode**



7.1.4 Operating mode transitions

State transitions are summarized in the state transition diagram in Figure 4 and detailed in Table 6 to Table 9. Numbers are used to represent the state transitions. The numbers in the diagram correspond to the numbers in the third column in the tables.

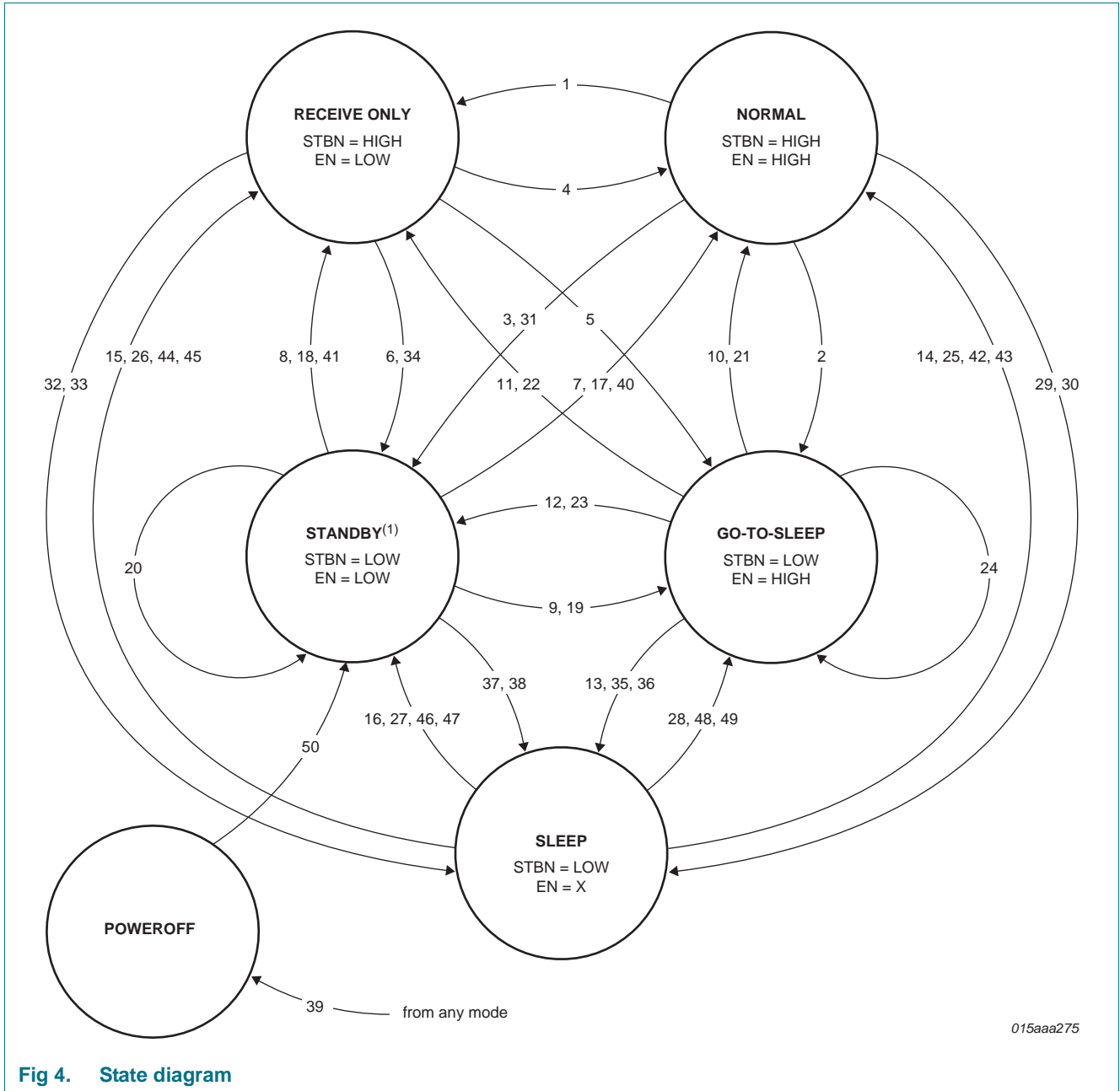


Fig 4. State diagram

**Table 6. State transitions forced by EN and STBN**

→ indicates the action that initiates a transaction; 1→ and 2 → indicated the consequences of a transaction.

| Transition from mode | Direction to mode | Transition number | Pin  |     | Flag              |                    |                   |         |         | Notes |
|----------------------|-------------------|-------------------|------|-----|-------------------|--------------------|-------------------|---------|---------|-------|
|                      |                   |                   | STBN | EN  | UV <sub>VIO</sub> | UV <sub>VBAT</sub> | UV <sub>VCC</sub> | PWON    | Wake    |       |
| Normal               | Receive-only      | 1                 | H    | → L | cleared           | cleared            | cleared           | cleared | X       |       |
|                      | Go-to-sleep       | 2                 | → L  | H   | cleared           | cleared            | cleared           | cleared | X       |       |
|                      | Standby           | 3                 | → L  | → L | cleared           | cleared            | cleared           | cleared | X       |       |
| Receive-only         | Normal            | 4                 | H    | → H | cleared           | cleared            | cleared           | X       | X       |       |
|                      | Go-to-sleep       | 5                 | → L  | → H | cleared           | cleared            | cleared           | X       | X       |       |
|                      | Standby           | 6                 | → L  | L   | cleared           | cleared            | cleared           | X       | X       |       |
| Standby              | Normal            | 7                 | → H  | → H | cleared           | cleared            | cleared           | X       | X       |       |
|                      | Receive-only      | 8                 | → H  | L   | cleared           | cleared            | cleared           | X       | X       |       |
|                      | Go-to-sleep       | 9                 | L    | → H | cleared           | cleared            | X                 | X       | X       |       |
| Go-to-sleep          | Normal            | 10                | → H  | H   | cleared           | cleared            | cleared           | X       | X       | [1]   |
|                      | Receive-only      | 11                | → H  | → L | cleared           | cleared            | cleared           | X       | X       | [1]   |
|                      | Standby           | 12                | L    | → L | cleared           | cleared            | X                 | X       | X       | [1]   |
|                      | Sleep             | 13                | L    | H   | cleared           | cleared            | X                 | X       | cleared | [2]   |
| Sleep                | Normal            | 14                | → H  | H   | cleared           | cleared            | cleared           | X       | X       |       |
|                      | Receive-only      | 15                | → H  | L   | cleared           | cleared            | cleared           | X       | X       |       |
|                      | Standby           | 16                | → H  | X   | cleared           | cleared            | X                 | X       | X       | [3]   |

[1] Hold time of go-to-sleep is less than  $t_{h(\text{gotosleep})}$ .

[2] Hold time of go-to-sleep becomes greater than  $t_{h(\text{gotosleep})}$ .

[3] Transition to a non-low-power mode is blocked when the voltage on pin  $V_{CC}$  is below  $V_{\text{uvd}(V_{CC})}$  for longer than  $t_{\text{det}(uv)(V_{CC})}$ .

**Table 7. State transitions forced by a wake-up**

→ indicates the action that initiates a transaction; 1 → and 2 → indicated the consequences of a transaction.

| Transition from mode | Direction to mode | Transition number | Pin  |    | Flag              |                    |                   |      |       | Note   |
|----------------------|-------------------|-------------------|------|----|-------------------|--------------------|-------------------|------|-------|--------|
|                      |                   |                   | STBN | EN | UV <sub>VIO</sub> | UV <sub>VBAT</sub> | UV <sub>VCC</sub> | PWON | Wake  |        |
| Standby              | Normal            | 17                | H    | H  | cleared           | cleared            | 1 → cleared       | X    | → set | [1]    |
|                      | Receive-only      | 18                | H    | L  | cleared           | cleared            | 1 → cleared       | X    | → set | [1]    |
|                      | Go-to-sleep       | 19                | L    | H  | cleared           | cleared            | 1 → cleared       | X    | → set | [1]    |
|                      | Standby           | 20                | L    | L  | cleared           | cleared            | 1 → cleared       | X    | → set | [1]    |
| Go-to-sleep          | Normal            | 21                | H    | H  | cleared           | cleared            | 1 → cleared       | X    | → set | [1]    |
|                      | Receive-only      | 22                | H    | L  | cleared           | cleared            | 1 → cleared       | X    | → set | [1]    |
|                      | Standby           | 23                | L    | L  | cleared           | cleared            | 1 → cleared       | X    | → set | [1]    |
|                      | Go-to-sleep       | 24                | L    | H  | cleared           | cleared            | 1 → cleared       | X    | → set | [1]    |
| Sleep                | Normal            | 25                | H    | H  | 1 → cleared       | 1 → cleared        | 1 → cleared       | X    | → set | [1][2] |
|                      | Receive-only      | 26                | H    | L  | 1 → cleared       | 1 → cleared        | 1 → cleared       | X    | → set | [1][2] |
|                      | Standby           | 27                | L    | L  | 1 → cleared       | 1 → cleared        | 1 → cleared       | X    | → set | [1]    |
|                      | Go-to-sleep       | 28                | L    | H  | 1 → cleared       | 1 → cleared        | 1 → cleared       | X    | → set | [1][2] |

[1] Setting the wake flag clears the UV<sub>VIO</sub>, UV<sub>VBAT</sub> and UV<sub>VCC</sub> flags.

[2] Transition via Standby mode.

**Table 8. State transitions forced by an undervoltage condition**

→ indicates the action that initiates a transaction; 1 → and 2 → indicated the consequences of a transaction.

| Transition from mode | Direction to mode | Transition number | Flag              |                    |                   |         |         | Note        |        |
|----------------------|-------------------|-------------------|-------------------|--------------------|-------------------|---------|---------|-------------|--------|
|                      |                   |                   | UV <sub>VIO</sub> | UV <sub>VBAT</sub> | UV <sub>VCC</sub> | PWON    | Wake    |             |        |
| Normal               | Sleep             | 29                | → set             | cleared            | cleared           | cleared | cleared | 1 → cleared | [1]    |
|                      | Sleep             | 30                | cleared           | → set              | cleared           | cleared | cleared | 1 → cleared | [1]    |
|                      | Standby           | 31                | cleared           | cleared            | → set             | cleared | cleared | 1 → cleared | [1][2] |
| Receive-only         | Sleep             | 32                | → set             | cleared            | cleared           | X       | X       | 1 → cleared | [1]    |
|                      | Sleep             | 33                | cleared           | → set              | cleared           | X       | X       | 1 → cleared | [1]    |
|                      | Standby           | 34                | cleared           | cleared            | → set             | X       | X       | 1 → cleared | [1][2] |
| Go-to-sleep          | Sleep             | 35                | → set             | cleared            | cleared           | X       | X       | 1 → cleared | [1]    |
|                      | Sleep             | 36                | cleared           | → set              | cleared           | X       | X       | 1 → cleared | [1]    |
| Standby              | Sleep             | 37                | → set             | cleared            | X                 | X       | X       | 1 → cleared | [1][3] |
|                      | Sleep             | 38                | cleared           | → set              | X                 | X       | X       | 1 → cleared | [1][4] |
| X                    | PowerOff          | 39                | X                 | X                  | X                 | X       | X       | X           | [5]    |

- [1] UV<sub>VIO</sub>, UV<sub>VBAT</sub> or UV<sub>VCC</sub> detected clears the wake flag.  
 [2] Transition already completed when the voltage on pin V<sub>CC</sub> is below V<sub>uvd(VCC)</sub> for longer than t<sub>det(uv)(VCC)</sub>.  
 [3] UV<sub>VIO</sub> overrules UV<sub>VCC</sub>.  
 [4] UV<sub>VBAT</sub> overrules UV<sub>VCC</sub>.  
 [5] V<sub>DIG</sub> (the internal digital supply voltage to the state machine) < V<sub>th(det)POR</sub>.

**Table 9. State transitions forced by an undervoltage recovery**  
 → indicates the action that initiates a transaction; →1 and →2 are the consequences of a transaction.

| Transition from mode | Direction to mode | Transition number | Pin  |           | Flag              |                    |                   |       |      | Note |
|----------------------|-------------------|-------------------|------|-----------|-------------------|--------------------|-------------------|-------|------|------|
|                      |                   |                   | STBN | EN        | UV <sub>VIO</sub> | UV <sub>VBAT</sub> | UV <sub>VCC</sub> | PWON  | Wake |      |
| Standby              | Normal            | 40                | H    | H         | cleared           | cleared            | → cleared         | X     | X    | [1]  |
|                      | Receive-only      | 41                | H    | L         | cleared           | cleared            | → cleared         | X     | X    | [1]  |
| Sleep                | Normal            | 42                | H    | H         | cleared           | → cleared          | cleared           | X     | X    |      |
|                      | Normal            | 43                | H    | H         | → cleared         | cleared            | cleared           | X     | X    |      |
|                      | Receive-only      | 44                | H    | L         | cleared           | → cleared          | cleared           | X     | X    |      |
|                      | Receive-only      | 45                | H    | L         | → cleared         | cleared            | cleared           | X     | X    |      |
|                      | Standby           | 46                | L    | L         | cleared           | → cleared          | cleared           | X     | X    |      |
|                      | Standby           | 47                | L    | L         | → cleared         | cleared            | cleared           | X     | X    |      |
|                      | Go-to-sleep       | 48                | L    | H         | cleared           | → cleared          | cleared           | X     | X    |      |
| Go-to-sleep          | 49                | L                 | H    | → cleared | cleared           | cleared            | X                 | X     |      |      |
| PowerOff             | Standby           | 50                | X    | X         | X                 | X                  | X                 | → set | X    | [2]  |

[1] Transition already completed when the voltage on pin V<sub>CC</sub> is above V<sub>uvr(VCC)</sub> for longer than t<sub>rec(uv)(VCC)</sub>.

[2] The voltage on pin V<sub>BAT</sub> is above V<sub>uvr(VBAT)</sub> for longer than t<sub>rec(uv)(VBAT)</sub> AND V<sub>DIG</sub> (the internal digital supply voltage to the state machine) > V<sub>th(rec)POR</sub>.

### 7.1.5 Normal mode

In Normal mode, the transceiver is able to transmit and receive data via bus lines BP and BM. The output of the normal receiver is connected directly to pin RXD.

Transmitter behavior in Normal mode, with no TXEN timeout (see [Section 7.4.7](#)) and the temperature flag not set (TEMP HIGH = 0; see [Table 11](#)), is detailed in [Table 10](#).

In this mode, pin INH is set HIGH.

**Table 10. Transmitter function table**

| BGE | TXEN | TXD | Transmitter   |
|-----|------|-----|---|
| L   | X    | X   | transmitter is disabled   |
| X   | H    | X   | transmitter is disabled   |
| H   | L    | H   | transmitter is enabled; the bus lines are actively driven; BP is driven HIGH and BM is driven LOW |
| H   | L    | L   | transmitter is enabled; the bus lines are actively driven; BP is driven LOW and BM is driven HIGH |

The first LOW level detected on pin TXD when pin BGE is HIGH and pin TXEN is LOW activates the transmitter.

### 7.1.6 Receive-only mode

In Receive-only mode, the transceiver can only receive data. The transmitter is disabled, regardless of the voltage levels on pins BGE and TXEN.

In this mode, pin INH is set HIGH.

### 7.1.7 Standby mode

Standby mode is a low-power mode featuring very low current consumption. In this mode, the transceiver cannot transmit or receive data. The low-power receiver is activated to monitor the bus for wake-up patterns.

A transition to Standby mode can be triggered by applying the appropriate levels on pins EN and STBN (see [Figure 4](#) and [Table 6](#)) or if an undervoltage is detected on pin V<sub>CC</sub> (see [Figure 4](#) and [Section 7.1.9](#)).

In this mode, pin INH is set HIGH.

If the wake flag is set, pins RXEN and RXD are driven LOW; otherwise pins RXEN and RXD are set HIGH (see [Section 7.2](#)).

### 7.1.8 Go-to-sleep mode

In this mode, the transceiver behaves as in Standby mode. If Go-to-sleep mode remains active longer than the go-to-sleep hold time ( $t_{h(\text{gotosleep})}$ ) and the wake flag has been cleared previously, the transceiver switches to Sleep mode regardless of the voltage on pin EN.

### 7.1.9 Sleep mode

Sleep mode is a low-power mode. The only difference between Sleep mode and Standby mode is that pin INH is set floating in Sleep mode. A transition to Sleep mode is triggered from all other modes when the UV<sub>VIO</sub> flag or the UV<sub>VBAT</sub> flag is set (see [Table 8](#)).

When the wake flag is set and  $V_{IO}$  is valid, the undervoltage flags are reset. The transceiver switches from Sleep mode to the mode indicated by the levels on pins EN and STBN (see [Table 8](#)).

## 7.2 Wake-up mechanism

From Sleep mode (pin INH floating), the transceiver enters Standby mode if the wake flag is set. Consequently, pin INH is switched on (HIGH).

If an undervoltage is not detected on pins  $V_{IO}$ ,  $V_{CC}$  or  $V_{BAT}$ , the transceiver switches immediately to the mode indicated by the levels on pins EN and STBN.

In Standby, Go-to-sleep and Sleep modes, pins RXD, RXEN and ERRN are driven LOW if the wake flag is set.

### 7.2.1 Remote wake-up

#### 7.2.1.1 Bus wake-up via wake-up pattern

A valid wake-up pattern on the bus triggers a remote wake-up. A valid remote wake-up pattern consists of a DATA\_0, DATA\_1 or idle, DATA\_0, DATA\_1 or idle sequence. The DATA\_0 phases must last at least  $t_{det(wake)DATA\_0}$  and the DATA\_1 or idle phases at least  $t_{det(wake)idle}$ . The entire sequence must be completed within  $t_{det(wake)tot}$ .

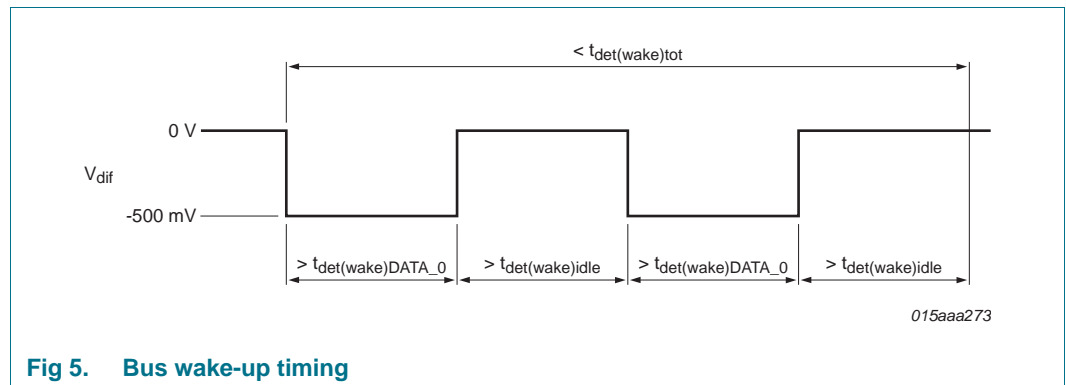


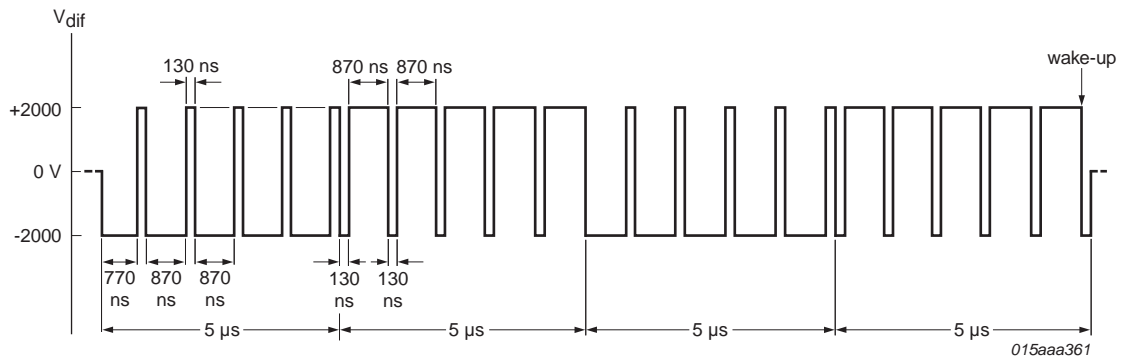
Fig 5. Bus wake-up timing

#### 7.2.1.2 Bus wake-up via dedicated FlexRay data frame

If the TJA1081G receives a dedicated data frame that emulates a valid wake-up pattern as detailed [Figure 6](#), the remote wake-up source flag is set.

Due to the Byte Start Sequence (BSS) preceding each byte, the DATA\_0 and DATA\_1 phases for the wake-up symbol are interrupted every 1  $\mu$ s. For 10 Mbit/s, the maximum interruption time is 130 ns. Such interruptions do not prevent the transceiver from recognizing the wake-up pattern in the payload of a data frame.

The remote wake-up source flag is not set if an invalid wake-up pattern is received.



Each interruption is 130 ns.

The transition time from DATA\_0 to DATA\_1 and from DATA\_1 to DATA\_0 is about 20 ns.

The following pattern sets the TJA1081G remote wake-up source flag:

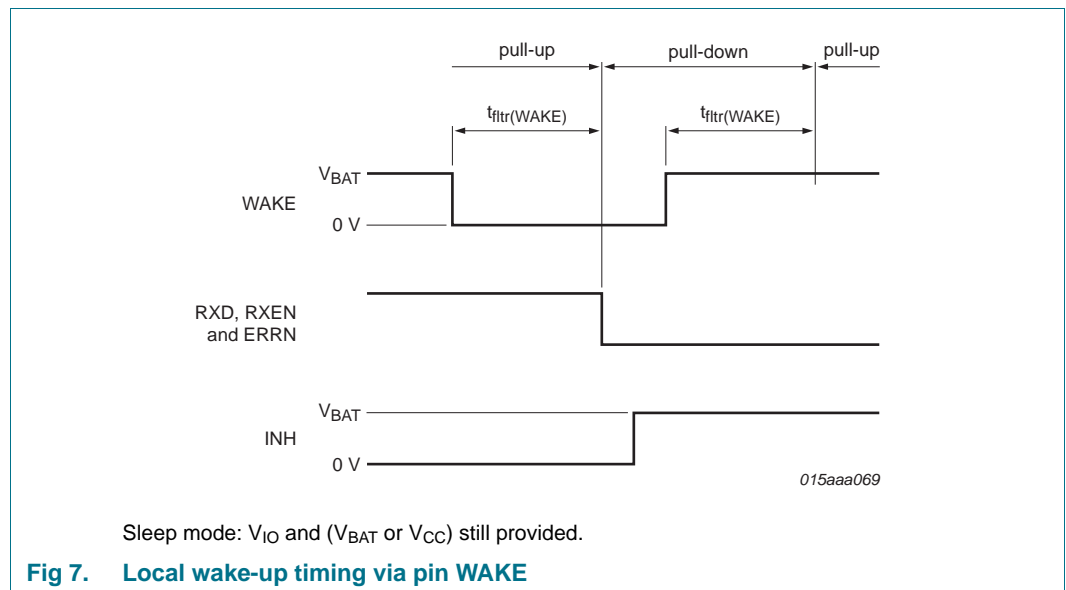
```
FFh, FFh, FFh, FFh, FFh, 00h, 00h, 00h, 00h, 00h,
FFh, FFh, FFh, FFh, FFh, 00h, 00h, 00h, 00h, 00h,
FFh, FFh, FFh, FFh, FFh, 00h, 00h, 00h, 00h, 00h,
FFh, FFh, FFh, FFh, FFh, FFh
```

Fig 6. Minimum bus pattern for bus wake-up

### 7.2.2 Local wake-up via pin WAKE

If the voltage on pin WAKE is lower than  $V_{th(det)(WAKE)}$  for longer than  $t_{ftr(WAKE)}$  (falling edge on pin WAKE), a local wake-up event on pin WAKE is detected. At the same time, the biasing of this pin is switched to pull-down.

If the voltage on pin WAKE is higher than  $V_{th(det)(WAKE)}$  for longer than  $t_{ftr(WAKE)}$ , the biasing of this pin is switched to pull up and a local wake-up is not detected.



Sleep mode:  $V_{IO}$  and ( $V_{BAT}$  or  $V_{CC}$ ) still provided.

Fig 7. Local wake-up timing via pin WAKE



### 7.3 Fail-silent behavior

To ensure fail-silent behavior, a reset mechanism for the digital state machine has been implemented along with undervoltage detection.

If an undervoltage is detected on pins  $V_{CC}$ ,  $V_{IO}$  and/or  $V_{BAT}$ , the transceiver switches to a low-power mode. This action ensures that the transmitter and receiver are passive when an undervoltage is detected and that their behavior is defined.

The digital state machine is supplied by  $V_{CC}$ ,  $V_{IO}$  or  $V_{BAT}$ . Therefore, the digital state machine is properly supplied as long as the voltage on pin  $V_{CC}$ ,  $V_{IO}$  or  $V_{BAT}$  remains above 4.5 V.

If the voltage on all pins (i.e.  $V_{CC}$ ,  $V_{IO}$  and  $V_{BAT}$ ) breaks down, a reset signal is transmitted to the digital state machine. The reset signal is transmitted as soon as the internal supply voltage to the digital state machine is no longer high enough to guarantee proper operation. This precaution ensures that the digital state machine is passive, and its behavior defined, when an undervoltage is detected.

#### 7.3.1 $V_{BAT}$ undervoltage

If the  $UV_{V_{BAT}}$  flag is set, the transceiver enters Sleep mode (pin INH is switched off) regardless of the voltage levels on pins EN and STBN. If the undervoltage recovers, the transceiver switches to the mode determined by the voltages on pins EN and STBN.

#### 7.3.2 $V_{CC}$ undervoltage

If the  $UV_{V_{CC}}$  flag is set, the transceiver switches to Standby mode regardless of the voltage levels on pins EN and STBN. If the undervoltage recovers or the wake flag is set, mode switching via pins EN and STBN is again enabled.

#### 7.3.3 $V_{IO}$ undervoltage

If the voltage on pin  $V_{IO}$  is lower than  $V_{uvd(V_{IO})}$  for longer than  $t_{det(uv)(V_{IO})}$  (even if the  $UV_{V_{IO}}$  flag is reset) pins EN, STBN, TXD and BGE are set LOW (internally) and pin TXEN is set HIGH (internally). If the  $UV_{V_{IO}}$  flag is set, the transceiver enters Sleep mode (pin INH is switched off). If the undervoltage recovers or the wake flag is set, mode switching via pins EN and STBN is again enabled.

### 7.4 Flags

#### 7.4.1 Local wake-up source flag

The local wake-up source flag can only be set in a low-power mode. When a wake-up event is detected on pin WAKE (see [Section 7.2.2](#)), the local wake-up source flag is set. The local wake-up source flag is reset by entering a low-power mode.

#### 7.4.2 Remote wake-up source flag

The remote wake-up source flag can only be set in a low-power mode if pin  $V_{BAT}$  is within its operating range. When a remote wake-up event is detected on the bus lines (see [Section 7.2.1](#)), the remote wake-up source flag is set. The remote wake-up source flag is reset by entering a low-power mode.

### 7.4.3 Wake flag

The wake flag is set if the local or remote wake-up source flag is set. The wake flag is reset by entering a low-power mode or by setting one of the undervoltage flags.

### 7.4.4 Power-on flag

If the internal supply voltage to the digital section rises above the minimum operating level, the PWON power-on flag is set. The PWON flag is reset when the TJA1081G enters Normal mode.

### 7.4.5 Temperature medium flag

If the junction temperature exceeds  $T_{j(\text{warn})(\text{medium})}$  in a normal-power mode, the temperature medium flag is set. The temperature medium flag is reset when the junction temperature drops below  $T_{j(\text{warn})(\text{medium})}$  (in a normal-power mode or after the status register has been read in a low-power mode). No action is taken when this flag is set.

### 7.4.6 Temperature high flag

If the junction temperature exceeds  $T_{j(\text{dis})(\text{high})}$  in a normal-power mode, the temperature high flag is set. If a negative edge is applied to pin TXEN while the junction temperature is below  $T_{j(\text{dis})(\text{high})}$  in a normal-power mode, the temperature high flag is reset.

The transmitter is disabled when the temperature high flag is set.

### 7.4.7 TXEN clamped flag

If pin TXEN is LOW for longer than  $t_{\text{detCL}}(\text{TXEN})$ , the TXEN clamped flag is set. If pin TXEN is HIGH, the TXEN clamped flag is reset. The transmitter is disabled when the TXEN clamped flag is set.

### 7.4.8 Bus error flag

The bus error flag is set if pin TXEN is LOW, pin BGE is HIGH and the data received on the bus lines (pins BP and BM) is different to that received on pin TXD. The transmission of any valid communication element, including a wake-up pattern, is not detected as a bus error.

The bus error flag is reset if the data on the bus lines (pins BP and BM) is the same as on pin TXD or if the transmitter is disabled. No action is taken when the bus error flag is set.

### 7.4.9 UV<sub>VBAT</sub> flag

If the voltage on pin V<sub>BAT</sub> is lower than  $V_{\text{uvd}}(\text{VBAT})$  for longer than  $t_{\text{det}(\text{uv})}(\text{VBAT})$ , the UV<sub>VBAT</sub> flag is set. The UV<sub>VBAT</sub> flag is reset if the voltage is higher than  $V_{\text{uvr}}(\text{VBAT})$  for longer than  $t_{\text{to}(\text{uvr})}(\text{VBAT})$  or by setting the wake flag; see [Section 7.3.1](#).

### 7.4.10 UV<sub>VCC</sub> flag

In a non-low-power mode, the UV<sub>VCC</sub> flag is set if the voltage on pin V<sub>CC</sub> is lower than  $V_{\text{uvd}}(\text{VCC})$  for longer than  $t_{\text{det}(\text{uv})}(\text{VCC})$ . In a low-power mode, the UV<sub>VCC</sub> flag is set if the voltage on pin V<sub>CC</sub> is lower than  $V_{\text{uvd}}(\text{VCC})$  for longer than  $t_{\text{to}(\text{uvd})}(\text{VCC})$ . The UV<sub>VCC</sub> flag is reset if the voltage on pin V<sub>CC</sub> is higher than  $V_{\text{uvr}}(\text{VCC})$  for longer than  $t_{\text{to}(\text{uvr})}(\text{VCC})$  or the wake flag is set; see [Section 7.3.2](#).

### 7.4.11 UV<sub>VIO</sub> flag

If the voltage on pin V<sub>IO</sub> is lower than V<sub>uvd(VIO)</sub> for longer than t<sub>to(ugd)(VIO)</sub>, the UV<sub>VIO</sub> flag is set. The UV<sub>VIO</sub> flag is reset if the voltage on pin V<sub>IO</sub> is higher than V<sub>uvr(VIO)</sub> for longer than t<sub>to(uvr)(VIO)</sub> or the wake flag is set; see [Section 7.3.3](#).

## 7.5 Status register

Pin ERRN goes LOW when one or more of status bits S4 to S10 is set. The contents of the status register ([Table 11](#)) can be read out on pin ERRN using the input signal on pin EN as a clock. The timing diagram is shown in [Figure 8](#).

The status register is accessible if:

- UV<sub>VIO</sub> flag is not set and the voltage on pin V<sub>IO</sub> is between 4.75 V and 5.25 V
- UV<sub>VCC</sub> flag is not set and the voltage on pin V<sub>IO</sub> is between 2.8 V and 4.75 V

If an edge is not detected on pin EN for t<sub>det(EN)</sub> after reading the status register, status bits S4 to S10 are cleared provided the corresponding flags have been reset.

**Table 11. Status bits**

| Bit number | Status bit    | Description  |
|------------|---------------|--|
| S0         | LOCAL WAKEUP  | local wake-up source flag is redirected to this bit                            |
| S1         | REMOTE WAKEUP | remote wake-up source flag is redirected to this bit                           |
| S2         | -             | not used; always set   |
| S3         | PWON          | status bit set means that PWON flag has been set previously                    |
| S4         | BUS ERROR     | status bit set means that bus error flag has been set previously               |
| S5         | TEMP HIGH     | status bit set means temperature high flag has been set previously             |
| S6         | TEMP MEDIUM   | status bit set means that temperature medium flag has been set previously      |
| S7         | TXEN CLAMPED  | status bit set means that TXEN clamped flag has been set previously            |
| S8         | UVVBAT        | status bit set means UV <sub>VBAT</sub> flag has been set previously           |
| S9         | UVVCC         | status bit set means UV <sub>VCC</sub> flag has been set previously            |
| S10        | UVVIO         | status bit set means UV <sub>VIO</sub> flag has been set previously            |
| S11        | BGE FEEDBACK  | BGE feedback (status bit reset if pin BGE LOW; status bit set if pin BGE HIGH) |
| S12        | -             | not used; always reset   |

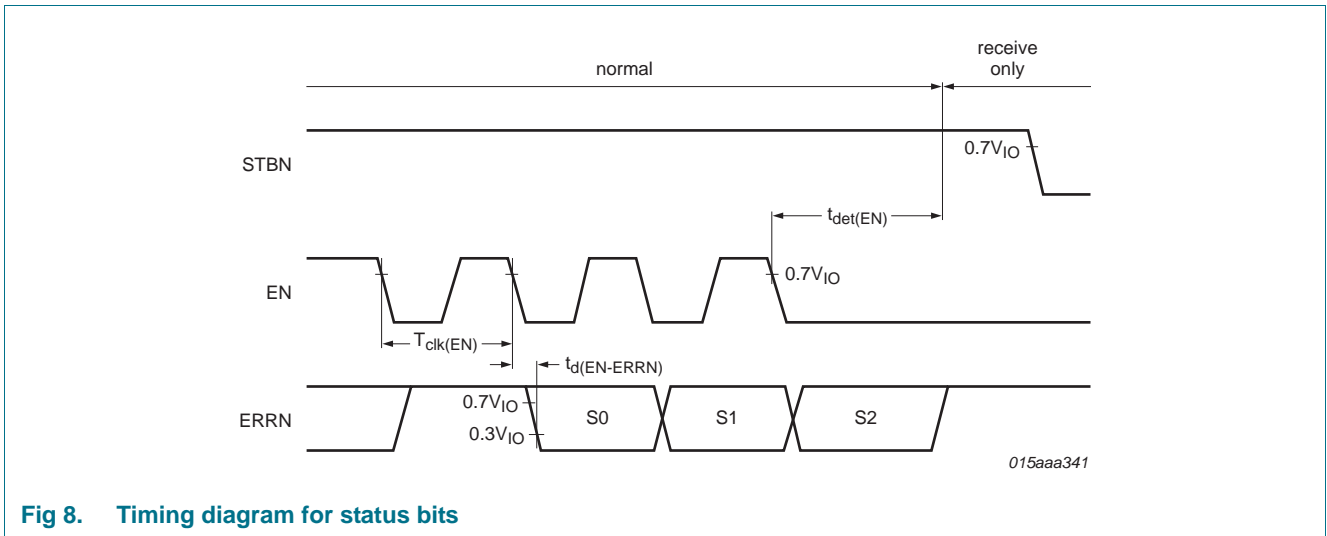


Fig 8. Timing diagram for status bits

## 8. Limiting values

**Table 12. Limiting values**

In accordance with the Absolute Maximum Rating System (IEC 60134). All voltages are referenced to ground.

| Symbol               | Parameter                       | Conditions  | Min  | Max                    | Unit |
|----------------------|---------------------------------|---|------|------------------------|------|
| V <sub>x</sub>       | voltage on pin x                | on pin V <sub>BAT</sub> [1]   | -0.3 | +60                    | V    |
|                      |                                 | on pins V <sub>CC</sub> , V <sub>IO</sub> , BGE, TXEN, TXD, EN and STBN [1]                 | -0.3 | +5.5                   | V    |
|                      |                                 | on pins INH, WAKE [1]   | -0.3 | V <sub>BAT</sub> + 0.3 | V    |
|                      |                                 | on pins ERRN, RXD and RXEN [1]  | -0.3 | V <sub>IO</sub> + 0.3  | V    |
|                      |                                 | on pins BP and BM with respect to pins V <sub>BAT</sub> , WAKE, INH, GND and each other [1] | -60  | +60                    | V    |
| I <sub>O(INH)</sub>  | output current on pin INH       |   | -1   | -                      | mA   |
| I <sub>O(WAKE)</sub> | output current on pin WAKE      | pin GND not connected   | -15  | -                      | mA   |
| V <sub>trt</sub>     | transient voltage               | on pins BM and BP [2]   |      |                        |      |
|                      |                                 | pulse 1   | -100 | -                      | V    |
|                      |                                 | pulse 2a  | -    | 75                     | V    |
|                      |                                 | pulse 3a  | -150 | -                      | V    |
|                      |                                 | pulse 3b  | -    | 100                    | V    |
| T <sub>stg</sub>     | storage temperature             |   | -55  | +150                   | °C   |
| T <sub>vj</sub>      | virtual junction temperature    | [3]   | -40  | +150                   | °C   |
| T <sub>amb</sub>     | ambient temperature             |   | -40  | +125                   | °C   |
| V <sub>ESD</sub>     | electrostatic discharge voltage | IEC 61000-4-2 (150 pF, 330 Ω) [4]   |      |                        |      |
|                      |                                 | on pins BP and BM to ground   | -6.0 | +6.0                   | kV   |
|                      |                                 | on pin V <sub>BAT</sub> to ground [5]   | -6.0 | +6.0                   | kV   |
|                      |                                 | on pin WAKE to ground [6]   | -6.0 | +6.0                   | kV   |
|                      |                                 | Human Body Model (HBM); 100 pF, 1.5 kΩ [7]  |      |                        |      |
|                      |                                 | on pins BP and BM to ground   | -6.0 | +6.0                   | kV   |
|                      |                                 | on pins V <sub>BAT</sub> and WAKE to ground   | -4.0 | +4.0                   | kV   |
|                      |                                 | on any other pin  | -2.0 | +2.0                   | kV   |
|                      |                                 | Machine Model (MM); 200 pF, 0.75 μH, 10 Ω; any pin [8]                                      | -100 | +100                   | V    |
|                      |                                 | Charged Device Model (CDM); field induced charge; 4 pF [9]                                  |      |                        |      |
|                      |                                 | on corner pins  | -750 | +750                   | V    |
| on any other pin     | -500                            | +500  | V    |                        |      |

- [1] The device can sustain voltages up to the specified values over the product lifetime, provided applied voltages (including transients) never exceed these values.
- [2] According to TS 62228 (2007), Section 4.2.4; parameters for standard pulses defined in ISO 7637-2:2004-09-15.
- [3] In accordance with IEC 60747-1. An alternative definition of T<sub>vj</sub> is:  $T_{vj} = T_{amb} + P \times R_{th(j-a)}$ , where R<sub>th(j-a)</sub> is a fixed value to be used for the calculation of T<sub>vj</sub>. The rating for T<sub>vj</sub> limits the allowable combinations of power dissipation (P) and ambient temperature (T<sub>amb</sub>).
- [4] According to TS 62228 (2007), Section 4.3; DIN EN IEC 61000-4-2.
- [5] With 100 nF from V<sub>BAT</sub> to GND.
- [6] With 3.3 kΩ in series.
- [7] According to AEC-Q100-002.
- [8] According to AEC-Q100-003.
- [9] According to AEC-Q100-011 Rev-C1. The classification level is C4B.

## 9. Thermal characteristics

Table 13. Thermal characteristics

| Symbol               | Parameter                                   | Conditions       | Typ    | Unit |
|----------------------|---|------------------|--------|------|
| R <sub>th(j-a)</sub> | thermal resistance from junction to ambient | dual-layer board | [1] 96 | K/W  |
|                      |   | four-layer board | [2] 72 | K/W  |

- [1] According to JEDEC JESD51-2, JESD51-3 and JESD51-5 at natural convection on 1s board with thermal via array under the exposed pad connected to the second copper layer.
- [2] According to JEDEC JESD51-2, JESD51-5 and JESD51-7 at natural convection on 2s2p board. Board with two inner copper layers (thickness: 35 μm) and thermal via array under the exposed pad connected to the first inner copper layer.

## 10. Static characteristics

Table 14. Static characteristics

All parameters are guaranteed for  $V_{BAT} = 4.45\text{ V to }60\text{ V}$ ;  $V_{CC} = 4.45\text{ V to }5.25\text{ V}$ ;  $V_{IO} = 2.55\text{ V to }5.25\text{ V}$ ;  $T_{vj} = -40\text{ °C to }+150\text{ °C}$ ;  $C_{bus} = 100\text{ pF}$ ;  $R_{bus} = 40\text{ }\Omega\text{ to }55\text{ }\Omega$  unless otherwise specified. All voltages are defined with respect to ground; positive currents flow into the IC.

| Symbol                     | Parameter   | Conditions  | Min   | Typ | Max   | Unit |
|----------------------------|---|---|-------|-----|-------|------|
| <b>Pin V<sub>BAT</sub></b> |   |   |       |     |       |      |
| V <sub>BAT</sub>           | battery supply voltage                                  |   | 4.75  | -   | 60    | V    |
| I <sub>BAT</sub>           | battery supply current                                  | low-power modes;<br>no load on pin INH  | -     | -   | 55    | μA   |
|                            |   | normal-power modes  | -     | -   | 1     | mA   |
| V <sub>uvd(VBAT)</sub>     | undervoltage detection voltage on pin V <sub>BAT</sub>  |   | 4.45  | -   | 4.715 | V    |
| V <sub>uvr(VBAT)</sub>     | undervoltage recovery voltage on pin V <sub>BAT</sub>   |   | 4.475 | -   | 4.74  | V    |
| V <sub>uvhys(VBAT)</sub>   | undervoltage hysteresis voltage on pin V <sub>BAT</sub> |   | 25    | -   | 290   | mV   |
| <b>Pin V<sub>CC</sub></b>  |   |   |       |     |       |      |
| V <sub>CC</sub>            | supply voltage  |   | 4.75  | -   | 5.25  | V    |
| I <sub>CC</sub>            | supply current  | low-power modes   | -1    | +2  | +10   | μA   |
|                            |   | Normal mode;<br>V <sub>BGE</sub> = 0 V; V <sub>TXEN</sub> = V <sub>IO</sub> ;<br>Receive-only mode      | -     | 13  | 21    | mA   |
|                            |   | Normal mode;<br>V <sub>BGE</sub> = V <sub>IO</sub> ; V <sub>TXEN</sub> = 0 V                            | -     | 37  | 50    | mA   |
|                            |   | Normal mode;<br>V <sub>BGE</sub> = V <sub>IO</sub> ; V <sub>TXEN</sub> = 0 V;<br>R <sub>bus</sub> = ∞ Ω | -     | 14  | 22    | mA   |
| V <sub>uvd(VCC)</sub>      | undervoltage detection voltage on pin V <sub>CC</sub>   |   | 4.45  | -   | 4.72  | V    |
| V <sub>uvr(VCC)</sub>      | undervoltage recovery voltage on pin V <sub>CC</sub>    |   | 4.47  | -   | 4.74  | V    |
| V <sub>uvhys(VCC)</sub>    | undervoltage hysteresis voltage on pin V <sub>CC</sub>  |   | 20    | -   | 290   | mV   |
| <b>Pin V<sub>IO</sub></b>  |   |   |       |     |       |      |
| V <sub>IO</sub>            | supply voltage on pin V <sub>IO</sub>                   |   | 2.8   | -   | 5.25  | V    |

**Table 14. Static characteristics ...continued**

All parameters are guaranteed for  $V_{BAT} = 4.45\text{ V to }60\text{ V}$ ;  $V_{CC} = 4.45\text{ V to }5.25\text{ V}$ ;  $V_{IO} = 2.55\text{ V to }5.25\text{ V}$ ;  $T_{vj} = -40\text{ °C to }+150\text{ °C}$ ;  $C_{bus} = 100\text{ pF}$ ;  $R_{bus} = 40\text{ }\Omega\text{ to }55\text{ }\Omega$  unless otherwise specified. All voltages are defined with respect to ground; positive currents flow into the IC.

| Symbol           | Parameter                                       | Conditions   | Min         | Typ | Max            | Unit          |
|------------------|---|--|-------------|-----|----------------|---------------|
| $I_{IO}$         | supply current on pin $V_{IO}$                  | low-power modes;<br>$V_{TXEN} = V_{IO}$  | -1          | +2  | +10            | $\mu\text{A}$ |
|                  |   | Normal and Receive-only modes; $V_{TXD} = V_{IO}$  | -           | -   | 1              | $\text{mA}$   |
| $I_{r(VIO)}$     | reverse current on pin $V_{IO}$                 | from digital input pins;<br>PowerOff mode;<br>$V_{TXEN} = 5.25\text{ V}$ ;<br>$V_{TXD} = 5.25\text{ V}$ ;<br>$V_{BGE} = 5.25\text{ V}$ ;<br>$V_{EN} = 5.25\text{ V}$ ;<br>$V_{STBN} = 5.25\text{ V}$ ;<br>$V_{CC} = V_{IO} = 0\text{ V}$ | -5          | -   | +5             | $\mu\text{A}$ |
| $V_{uvd(VIO)}$   | undervoltage detection voltage on pin $V_{IO}$  |  | 2.55        | -   | 2.765          | V             |
| $V_{uvr(VIO)}$   | undervoltage recovery voltage on pin $V_{IO}$   |  | 2.575       | -   | 2.79           | V             |
| $V_{uvhys(VIO)}$ | undervoltage hysteresis voltage on pin $V_{IO}$ |  | 25          | -   | 240            | $\text{mV}$   |
| <b>Pin EN</b>    |   |  |             |     |                |               |
| $V_{IH}$         | HIGH-level input voltage                        |  | $0.7V_{IO}$ | -   | 5.5            | V             |
| $V_{IL}$         | LOW-level input voltage                         |  | -0.3        | -   | $0.3V_{IO}$    | V             |
| $I_{IH}$         | HIGH-level input current                        | $V_{EN} = 0.7V_{IO}$   | 3           | -   | 15             | $\mu\text{A}$ |
| $I_{IL}$         | LOW-level input current                         | $V_{EN} = 0\text{ V}$  | -1          | 0   | +1             | $\mu\text{A}$ |
| <b>Pin STBN</b>  |   |  |             |     |                |               |
| $V_{IH}$         | HIGH-level input voltage                        |  | $0.7V_{IO}$ | -   | 5.5            | V             |
| $V_{IL}$         | LOW-level input voltage                         |  | -0.3        | -   | $0.3V_{IO}$    | V             |
| $I_{IH}$         | HIGH-level input current                        | $V_{STBN} = 0.7V_{IO}$   | 3           | -   | 15             | $\mu\text{A}$ |
| $I_{IL}$         | LOW-level input current                         | $V_{STBN} = 0\text{ V}$  | -1          | 0   | +1             | $\mu\text{A}$ |
| <b>Pin TXEN</b>  |   |  |             |     |                |               |
| $V_{IH}$         | HIGH-level input voltage                        |  | $0.7V_{IO}$ | -   | 5.5            | V             |
| $V_{IL}$         | LOW-level input voltage                         |  | -0.3        | -   | $0.3V_{IO}$    | V             |
| $I_{IH}$         | HIGH-level input current                        | $V_{TXEN} = V_{IO}$  | -1          | 0   | +1             | $\mu\text{A}$ |
| $I_{IL}$         | LOW-level input current                         | $V_{TXEN} = 0.3V_{IO}$   | -300        | -   | -50            | $\mu\text{A}$ |
| $I_L$            | leakage current                                 | $V_{TXEN} = 5.25\text{ V}$ ; $V_{IO} = 0\text{ V}$   | -1          | 0   | +1             | $\mu\text{A}$ |
| <b>Pin BGE</b>   |   |  |             |     |                |               |
| $V_{IH}$         | HIGH-level input voltage                        |  | $0.7V_{IO}$ | -   | 5.5            | V             |
| $V_{IL}$         | LOW-level input voltage                         |  | -0.3        | -   | $0.3V_{IO}$    | V             |
| $I_{IH}$         | HIGH-level input current                        | $V_{BGE} = 0.7V_{IO}$  | 3           | -   | 15             | $\mu\text{A}$ |
| $I_{IL}$         | LOW-level input current                         | $V_{BGE} = 0\text{ V}$   | -1          | 0   | +1             | $\mu\text{A}$ |
| <b>Pin TXD</b>   |   |  |             |     |                |               |
| $V_{IH}$         | HIGH-level input voltage                        | normal-power modes   | $0.6V_{IO}$ | -   | $V_{IO} + 0.3$ | V             |
| $V_{IL}$         | LOW-level input voltage                         | normal-power modes   | -0.3        | -   | $0.4V_{IO}$    | V             |
| $I_{IH}$         | HIGH-level input current                        | $V_{TXD} = V_{IO}$   | 3           | -   | 15             | $\mu\text{A}$ |

**Table 14. Static characteristics ...continued**

All parameters are guaranteed for  $V_{BAT} = 4.45\text{ V}$  to  $60\text{ V}$ ;  $V_{CC} = 4.45\text{ V}$  to  $5.25\text{ V}$ ;  $V_{IO} = 2.55\text{ V}$  to  $5.25\text{ V}$ ;  $T_{vj} = -40\text{ }^{\circ}\text{C}$  to  $+150\text{ }^{\circ}\text{C}$ ;  $C_{bus} = 100\text{ pF}$ ;  $R_{bus} = 40\text{ }\Omega$  to  $55\text{ }\Omega$  unless otherwise specified. All voltages are defined with respect to ground; positive currents flow into the IC.

| Symbol          | Parameter                 | Conditions  | Min                | Typ | Max      | Unit          |
|-----------------|---------------------------|---|--------------------|-----|----------|---------------|
| $I_{IL}$        | LOW-level input current   | normal-power modes;<br>$V_{TXD} = 0\text{ V}$   | -5                 | 0   | +5       | $\mu\text{A}$ |
|                 |                           | low-power modes   | -1                 | 0   | +1       | $\mu\text{A}$ |
| $I_{LI}$        | input leakage current     | $V_{TXD} = 5.25\text{ V}$ ; $V_{IO} = 0\text{ V}$   | -1                 | 0   | +1       | $\mu\text{A}$ |
| $C_i$           | input capacitance         | not tested; with respect to all other pins at ground;<br>$V_{TXD} = 100\text{ mV}$ ; $f = 5\text{ MHz}$ | [1] -              | 5   | 10       | pF            |
| <b>Pin RXD</b>  |                           |   |                    |     |          |               |
| $I_{OH}$        | HIGH-level output current | $V_{RXD} = V_{IO} - 0.4\text{ V}$ ;<br>$V_{IO} = V_{CC}$  | -20                | -   | -1       | mA            |
| $I_{OL}$        | LOW-level output current  | $V_{RXD} = 0.4\text{ V}$  | 1                  | -   | 20       | mA            |
| $V_{OH}$        | HIGH-level output voltage | $I_{OH(RXD)} = -1\text{ mA}$  | [1] $V_{IO} - 0.4$ | -   | $V_{IO}$ | V             |
| $V_{OL}$        | LOW-level output voltage  | $I_{OL(RXD)} = 1\text{ mA}$   | [1] -              | -   | 0.4      | V             |
| $V_O$           | output voltage            | when undervoltage on $V_{IO}$ ; $V_{CC} \geq 4.75\text{ V}$ ;<br>$R_L = 100\text{ k}\Omega$ to ground   | -                  | -   | 0.5      | V             |
|                 |                           | $R_L = 100\text{ k}\Omega$ to $V_{IO}$ ;<br>power off   | $V_{IO} - 0.5$     | -   | $V_{IO}$ | V             |
| <b>Pin ERRN</b> |                           |   |                    |     |          |               |
| $I_{OH}$        | HIGH-level output current | $V_{ERRN} = V_{IO} - 0.4\text{ V}$ ;<br>$V_{IO} = V_{CC}$   | -8                 | -3  | -0.5     | mA            |
| $I_{OL}$        | LOW-level output current  | $V_{ERRN} = 0.4\text{ V}$   | 0.5                | 2   | 8        | mA            |
| $V_{OH}$        | HIGH-level output voltage | $I_{OH(ERRN)} = -0.5\text{ mA}$   | [1] $V_{IO} - 0.4$ | -   | $V_{IO}$ | V             |
| $V_{OL}$        | LOW-level output voltage  | $I_{OL(ERRN)} = 0.5\text{ mA}$  | [1] -              | -   | 0.4      | V             |
| $I_L$           | leakage current           | $0\text{ V} \leq V_{ERRN} \leq V_{IO}$ ;<br>power off   | -5                 | 0   | +5       | $\mu\text{A}$ |
| $V_O$           | output voltage            | when undervoltage on $V_{IO}$ ; $V_{CC} > 4.75\text{ V}$ ;<br>$R_L = 100\text{ k}\Omega$ to ground      | -                  | -   | 0.5      | V             |
|                 |                           | $R_L = 100\text{ k}\Omega$ to ground;<br>power off  | -                  | -   | 0.5      | V             |
| <b>Pin RXEN</b> |                           |   |                    |     |          |               |
| $I_{OH}$        | HIGH-level output current | $V_{RXEN} = V_{IO} - 0.4\text{ V}$ ;<br>$V_{IO} = V_{CC}$   | -8                 | -3  | -0.5     | mA            |
| $I_{OL}$        | LOW-level output current  | $V_{RXEN} = 0.4\text{ V}$   | 0.5                | 2   | 8        | mA            |
| $V_{OH}$        | HIGH-level output voltage | $I_{OH(RXEN)} = -0.5\text{ mA}$   | [1] $V_{IO} - 0.4$ | -   | $V_{IO}$ | V             |
| $V_{OL}$        | LOW-level output voltage  | $I_{OL(RXEN)} = 0.5\text{ mA}$  | [1] -              | -   | 0.4      | V             |
| $I_L$           | leakage current           | $0\text{ V} \leq V_{RXEN} \leq V_{IO}$ ;<br>power off   | -5                 | 0   | +5       | $\mu\text{A}$ |



**Table 14. Static characteristics ...continued**

All parameters are guaranteed for  $V_{BAT} = 4.45\text{ V to }60\text{ V}$ ;  $V_{CC} = 4.45\text{ V to }5.25\text{ V}$ ;  $V_{IO} = 2.55\text{ V to }5.25\text{ V}$ ;  $T_{vj} = -40\text{ °C to }+150\text{ °C}$ ;  $C_{bus} = 100\text{ pF}$ ;  $R_{bus} = 40\text{ }\Omega\text{ to }55\text{ }\Omega$  unless otherwise specified. All voltages are defined with respect to ground; positive currents flow into the IC.

| Symbol                     | Parameter  | Conditions   | Min            | Typ         | Max         | Unit |
|----------------------------|--|--|----------------|-------------|-------------|------|
| $V_O$                      | output voltage   | when undervoltage on $V_{IO}$ ; $V_{CC} > 4.75\text{ V}$ ; $R_L = 100\text{ k}\Omega$ to ground  | -              | -           | 0.5         | V    |
|                            |  | $R_L = 100\text{ k}\Omega$ to $V_{IO}$ ; power off   | $V_{IO} - 0.5$ | -           | $V_{IO}$    | V    |
| <b>Pins BP and BM</b>      |  |  |                |             |             |      |
| $V_{o(idle)(BP)}$          | idle output voltage on pin BP  | Normal or Receive-only mode; $V_{TXEN} = V_{IO}$ ; $4.5\text{ V} \leq V_{CC} \leq 5.25\text{ V}$ | $0.4V_{CC}$    | $0.5V_{CC}$ | $0.6V_{CC}$ | V    |
|                            |  | Standby, Go-to-sleep or Sleep mode   | -0.1           | 0           | +0.1        | V    |
| $V_{o(idle)(BM)}$          | idle output voltage on pin BM  | Normal or Receive-only mode; $V_{TXEN} = V_{IO}$ ; $4.5\text{ V} \leq V_{CC} \leq 5.25\text{ V}$ | $0.4V_{CC}$    | $0.5V_{CC}$ | $0.6V_{CC}$ | V    |
|                            |  | Standby, Go-to-sleep or Sleep mode   | -0.1           | 0           | +0.1        | V    |
| $I_{o(idle)BP}$            | idle output current on pin BP  | $-60\text{ V} \leq V_{BP} \leq +60\text{ V}$ ; with respect to ground and $V_{BAT}$              | -7.5           | -           | +7.5        | mA   |
| $I_{o(idle)BM}$            | idle output current on pin BM  | $-60\text{ V} \leq V_{BM} \leq +60\text{ V}$ ; with respect to ground and $V_{BAT}$              | -7.5           | -           | +7.5        | mA   |
| $V_{o(idle)(dif)}$         | differential idle output voltage                                       |  | [2] -25        | 0           | +25         | mV   |
| $V_{OH(dif)}$              | differential HIGH-level output voltage                                 | $4.75\text{ V} \leq V_{CC} \leq 5.25\text{ V}$   | [2] 600        | -           | 2000        | mV   |
|                            |  | $4.45\text{ V} \leq V_{CC} \leq 5.25\text{ V}$   | [2] 530        | -           | 2000        | mV   |
| $V_{OL(dif)}$              | differential LOW-level output voltage                                  | $4.75\text{ V} \leq V_{CC} \leq 5.25\text{ V}$   | [2] -2000      | -           | -600        | mV   |
|                            |  | $4.45\text{ V} \leq V_{CC} \leq 5.25\text{ V}$   | [2] -2000      | -           | -530        | mV   |
| $V_{IH(dif)}$              | differential HIGH-level input voltage                                  | normal-power modes; $-10\text{ V} \leq V_{cm} \leq +15\text{ V}$ ; see <a href="#">Figure 10</a> | [3] [4] 150    | 210         | 300         | mV   |
|                            |  | normal-power modes; $-10\text{ V} \leq V_{cm} \leq +15\text{ V}$ ; see <a href="#">Figure 10</a> | [3] [4] -300   | -210        | -150        | mV   |
| $V_{IL(dif)}$              | differential LOW-level input voltage                                   | normal-power modes; $-10\text{ V} \leq V_{cm} \leq +15\text{ V}$ ; see <a href="#">Figure 10</a> | [3] [4] -300   | -210        | -150        | mV   |
|                            |  | low-power modes; see <a href="#">Figure 10</a>   | [4] -400       | -300        | -100        | mV   |
| $ \Delta V_{i(dif)(H-L)} $ | differential input volt. diff. betw. HIGH- and LOW-levels (abs. value) | normal-power modes; $V_{cm} = 2.5\text{ V}$  | [4] -30        | -           | +30         | mV   |
| $ V_{i(dif)det(act)} $     | activity detection differential input voltage (absolute value)         | normal-power modes   | 150            | 210         | 300         | mV   |

**Table 14. Static characteristics ...continued**

All parameters are guaranteed for  $V_{BAT} = 4.45\text{ V to }60\text{ V}$ ;  $V_{CC} = 4.45\text{ V to }5.25\text{ V}$ ;  $V_{IO} = 2.55\text{ V to }5.25\text{ V}$ ;  $T_{vj} = -40\text{ °C to }+150\text{ °C}$ ;  $C_{bus} = 100\text{ pF}$ ;  $R_{bus} = 40\text{ }\Omega\text{ to }55\text{ }\Omega$  unless otherwise specified. All voltages are defined with respect to ground; positive currents flow into the IC.

| Symbol                | Parameter  | Conditions   | Min         | Typ         | Max         | Unit       |               |
|-----------------------|--|--|-------------|-------------|-------------|------------|---------------|
| $I_{O(sc)}$           | short-circuit output current (absolute value)            | on pin BP;<br>$-5\text{ V} \leq V_{BP} \leq +60\text{ V}$<br>$R_{sc} \leq 1\text{ }\Omega$ ; $t_{sc} \geq 1500\text{ }\mu\text{s}$ | [5]<br>[6]  | -           | -           | 60         | mA            |
|                       |  | on pin BM;<br>$-5\text{ V} \leq V_{BM} \leq +60\text{ V}$<br>$R_{sc} \leq 1\text{ }\Omega$ ; $t_{sc} \geq 1500\text{ }\mu\text{s}$ | [5]<br>[6]  | -           | -           | 60         | mA            |
|                       |  | on pins BP and BM;<br>$R_{sc} \leq 1\text{ }\Omega$ ; $t_{sc} \geq 1500\text{ }\mu\text{s}$ ;<br>$V_{BP} = V_{BM}$                 | [5]<br>[6]  | -           | -           | 60         | mA            |
| $R_{i(BP)}$           | input resistance on pin BP                               | idle level; $R_{bus} = \infty\text{ }\Omega$   | 10          | 18          | 40          | k $\Omega$ |               |
| $R_{i(BM)}$           | input resistance on pin BM                               | idle level; $R_{bus} = \infty\text{ }\Omega$   | 10          | 18          | 40          | k $\Omega$ |               |
| $R_{i(dif)(BP-BM)}$   | differential input resistance between pin BP and pin BM  | idle level; $R_{bus} = \infty\text{ }\Omega$   | 20          | 36          | 80          | k $\Omega$ |               |
| $I_{L(BP)}$           | input leakage current on pin BP                          | power off;<br>$V_{BP} = V_{BM} = 5\text{ V}$ ; all other pins connected to GND;<br>GND connected to 0 V                            |             | -5          | 0           | +5         | $\mu\text{A}$ |
|                       |  | loss of ground;<br>$V_{BP} = V_{BM} = 0\text{ V}$ ;<br>all other pins connected to 16 V via 0 $\Omega$                             | [1]         | -1600       |             | +1600      | $\mu\text{A}$ |
| $I_{L(BM)}$           | input leakage current on pin BM                          | power off;<br>$V_{BP} = V_{BM} = 5\text{ V}$ ; all other pins connected to GND;<br>GND connected to 0 V                            |             | -5          | 0           | +5         | $\mu\text{A}$ |
|                       |  | loss of ground;<br>$V_{BP} = V_{BM} = 0\text{ V}$ ;<br>all other pins connected to 16 V via 0 $\Omega$                             | [1]         | -1600       |             | +1600      | $\mu\text{A}$ |
| $V_{cm(bus)(DATA_0)}$ | DATA_0 bus common-mode voltage                           |  | $0.4V_{CC}$ | $0.5V_{CC}$ | $0.6V_{CC}$ | V          |               |
| $V_{cm(bus)(DATA_1)}$ | DATA_1 bus common-mode voltage                           |  | $0.4V_{CC}$ | $0.5V_{CC}$ | $0.6V_{CC}$ | V          |               |
| $\Delta V_{cm(bus)}$  | bus common-mode voltage difference                       |  | -30         | 0           | +30         | mV         |               |
| $C_{i(BP)}$           | input capacitance on pin BP                              | with respect to all other pins at ground; $V_{BP} = 100\text{ mV}$ ; $f = 5\text{ MHz}$  | [1]         | -           | 8           | 15         | pF            |
| $C_{i(BM)}$           | input capacitance on pin BM                              | with respect to all other pins at ground; $V_{BM} = 100\text{ mV}$ ; $f = 5\text{ MHz}$  | [1]         | -           | 8           | 15         | pF            |
| $C_{i(dif)(BP-BM)}$   | differential input capacitance between pin BP and pin BM | with respect to all other pins at ground;<br>$V_{(BM-BP)} = 100\text{ mV}$ ;<br>$f = 5\text{ MHz}$                                 | [1]         | -           | 2           | 5          | pF            |
| $Z_{o(eq)TX}$         | transmitter equivalent output impedance                  | Normal mode;<br>$R_{bus} = 40\text{ }\Omega\text{ or }100\text{ }\Omega$ ;<br>$C_{bus} = 100\text{ pF}$                            | [1]<br>[7]  | 35          | -           | 100        | $\Omega$      |

**Table 14. Static characteristics ...continued**

All parameters are guaranteed for  $V_{BAT} = 4.45\text{ V to }60\text{ V}$ ;  $V_{CC} = 4.45\text{ V to }5.25\text{ V}$ ;  $V_{IO} = 2.55\text{ V to }5.25\text{ V}$ ;  $T_{vj} = -40\text{ °C to }+150\text{ °C}$ ;  $C_{bus} = 100\text{ pF}$ ;  $R_{bus} = 40\text{ }\Omega\text{ to }55\text{ }\Omega$  unless otherwise specified. All voltages are defined with respect to ground; positive currents flow into the IC.

| Symbol                        | Parameter                                  | Conditions   | Min             | Typ             | Max       | Unit               |
|-------------------------------|--|--|-----------------|-----------------|-----------|--------------------|
| <b>Pin INH</b>                |  |  |                 |                 |           |                    |
| $V_{OH(INH)}$                 | HIGH-level output voltage on pin INH       | $I_{INH} = -0.2\text{ mA}$   | $V_{BAT} - 0.8$ | $V_{BAT} - 0.3$ | $V_{BAT}$ | V                  |
|                               |  | $I_{INH} = -1\text{ mA}$ ; $V_{BAT} \geq 5.5\text{ V}$   | $V_{BAT} - 4$   | -               | $V_{BAT}$ | V                  |
| $I_{L(INH)}$                  | leakage current on pin INH                 | Sleep mode   | -5              | 0               | +5        | $\mu\text{A}$      |
| $I_{OL(INH)}$                 | LOW-level output current on pin INH        | $V_{INH} = 0\text{ V}$   | -7              | -4              | -1        | mA                 |
| <b>Pin WAKE</b>               |  |  |                 |                 |           |                    |
| $V_{th(det)(WAKE)}$           | detection threshold voltage on pin WAKE    | low-power mode   | 2               | -               | 3.75      | V                  |
| $V_{hys}$                     | hysteresis voltage                         |  | 0.3             | -               | 1.2       | V                  |
| $I_{IL}$                      | LOW-level input current                    | $V_{WAKE} = 2\text{ V}$ for $t > t_{ftr(WAKE)}$  | 3               | -               | 11        | $\mu\text{A}$      |
|                               |  | $V_{WAKE} = 0\text{ V}$  | -2              | -               | -0.3      | $\mu\text{A}$      |
| $I_{IH}$                      | HIGH-level input current                   | $V_{WAKE} = 3.75\text{ V}$ for $t > t_{ftr(WAKE)}$ ; $4.75\text{ V} \leq V_{BAT} \leq 60\text{ V}$ | -11             | -               | -3        | $\mu\text{A}$      |
|                               |  | $V_{WAKE} = V_{BAT}$   | 0.2             | -               | 2         | $\mu\text{A}$      |
| <b>Temperature protection</b> |  |  |                 |                 |           |                    |
| $T_{j(warn)(medium)}$         | medium warning junction temperature        | $V_{BAT} > 5.5\text{ V}$   | 155             | 165             | 175       | $^{\circ}\text{C}$ |
| $T_{j(dis)(high)}$            | high disable junction temperature          | $V_{BAT} > 5.5\text{ V}$   | 180             | 190             | 200       | $^{\circ}\text{C}$ |
| <b>Power-on reset</b>         |  |  |                 |                 |           |                    |
| $V_{th(det)POR}$              | power-on reset detection threshold voltage | of internal digital circuitry  | 3.0             | -               | 3.4       | V                  |
| $V_{th(rec)POR}$              | power-on reset recovery threshold voltage  | of internal digital circuitry  | 3.1             | -               | 3.5       | V                  |
| $V_{hys(POR)}$                | power-on reset hysteresis voltage          | of internal digital circuitry  | 100             | -               | 500       | mV                 |

- [1] Not tested in production; guaranteed by design.
- [2] Values also guaranteed when the signal on TXD is constant for between 100 ns and 4400 ns before the first edge.
- [3] Activity detected previously.
- [4]  $V_{cm}$  is the BP/BM common mode voltage.
- [5]  $R_{sc}$  is the short-circuit resistance; voltage difference between bus pins BP and BM is 60 V max.
- [6]  $t_{sc}$  is the minimum duration of the short circuit.
- [7]  $Z_{o(eq)TX} = 50\text{ }\Omega \times (V_{bus(100)} - V_{bus(40)}) / (2.5 \times V_{bus(40)} - V_{bus(100)})$  where:
  - $V_{bus(100)}$  is the differential output voltage on a load of 100  $\Omega$  and 100 pF in parallel
  - $V_{bus(40)}$  is the differential output voltage on a load of 40  $\Omega$  and 100 pF in parallel when driving a DATA\_1.

## 11. Dynamic characteristics

**Table 15. Dynamic characteristics**

All parameters are guaranteed for  $V_{BAT} = 4.45\text{ V to }60\text{ V}$ ;  $V_{CC} = 4.45\text{ V to }5.25\text{ V}$ ;  $V_{IO} = 2.55\text{ V to }5.25\text{ V}$ ;  $T_{vj} = -40\text{ }^{\circ}\text{C to }+150\text{ }^{\circ}\text{C}$ ;  $C_{bus} = 100\text{ pF}$ ;  $R_{bus} = 40\text{ }\Omega\text{ to }55\text{ }\Omega$  unless otherwise specified. All voltages are defined with respect to ground; positive currents flow into the IC.

| Symbol                          | Parameter  | Conditions   | Min               | Typ | Max | Unit  |    |
|---------------------------------|--|--|-------------------|-----|-----|-------|----|
| <b>Pins BP and BM</b>           |  |  |                   |     |     |       |    |
| $t_{d(\text{TXD-bus})}$         | delay time from TXD to bus                         | Normal mode; see <a href="#">Figure 9</a>  | [1]<br>[2]        |     |     |       |    |
|                                 |  | DATA_0   |                   | -   | -   | 60    | ns |
|                                 |  | DATA_1   |                   | -   | -   | 60    | ns |
| $\Delta t_{d(\text{TXD-bus})}$  | delay time difference from TXD to bus              | Normal mode; between DATA_0 and DATA_1; see <a href="#">Figure 10</a>  | [1]<br>[2]<br>[3] | -4  | -   | +4    | ns |
| $t_{d(\text{bus-RXD})}$         | delay time from bus to RXD                         | Normal mode; $V_{cm} = 2.5\text{ V}$ ; $C_{RXD} = 25\text{ pF}$ ; see <a href="#">Figure 10</a>                            | [3]               |     |     |       |    |
|                                 |  | DATA_0   |                   | -   | -   | 75    | ns |
|                                 |  | DATA_1   |                   | -   | -   | 75    | ns |
| $\Delta t_{d(\text{bus-RXD})}$  | delay time difference from bus to RXD              | Normal mode; $V_{cm} = 2.5\text{ V}$ ; $C_{RXD} = 25\text{ pF}$ ; between DATA_0 and DATA_1; see <a href="#">Figure 10</a> | [3]               | -5  | -   | +5    | ns |
| $t_{d(\text{TXEN-busidle})}$    | delay time from TXEN to bus idle                   | Normal mode; see <a href="#">Figure 9</a>  |                   | -   | 50  | 75    | ns |
| $t_{d(\text{TXEN-busact})}$     | delay time from TXEN to bus active                 | Normal mode; see <a href="#">Figure 9</a>  |                   | -   | 51  | 75    | ns |
| $\Delta t_{d(\text{TXEN-bus})}$ | delay time difference from TXEN to bus             | Normal mode; between TXEN-to-bus active and TXEN-to-bus idle; TXD LOW; see <a href="#">Figure 9</a>                        |                   | -50 | -   | +50   | ns |
| $t_{d(\text{BGE-busidle})}$     | delay time from BGE to bus idle                    | Normal mode; see <a href="#">Figure 9</a>  |                   | -   | 50  | 75    | ns |
| $t_{d(\text{BGE-busact})}$      | delay time from BGE to bus active                  | Normal mode; see <a href="#">Figure 9</a>  |                   | -   | 53  | 75    | ns |
| $t_{d(\text{TXENH-RXDH})}$      | delay time from TXEN HIGH to RXD HIGH              | Normal mode; TXD LOW   |                   | -   | -   | 325   | ns |
| <b>Bus slope</b>                |  |  |                   |     |     |       |    |
| $t_{r(\text{dif})(\text{bus})}$ | bus differential rise time                         | 20 % to 80 %   | [1]               | 6   | -   | 18.75 | ns |
|                                 |  | DATA_0 to idle; -300 mV to -30 mV; Normal mode   |                   | -   | -   | 30    | ns |
| $t_{f(\text{dif})(\text{bus})}$ | bus differential fall time                         | 80 % to 20 %   | [1]               | 6   | -   | 18.75 | ns |
|                                 |  | idle to DATA_0; -30 mV to -300 mV; Normal mode   |                   | -   | -   | 30    | ns |
|                                 |  | DATA_1 to idle; 300 mV to 30 mV; Normal mode   |                   | -   | -   | 30    | ns |
| $\Delta t_{(r-f)(\text{dif})}$  | difference between differential rise and fall time | 80 % to 20 %   |                   | -3  | -   | +3    | ns |

**Table 15. Dynamic characteristics ...continued**

All parameters are guaranteed for  $V_{BAT} = 4.45\text{ V to }60\text{ V}$ ;  $V_{CC} = 4.45\text{ V to }5.25\text{ V}$ ;  $V_{IO} = 2.55\text{ V to }5.25\text{ V}$ ;  $T_{vj} = -40\text{ }^{\circ}\text{C to }+150\text{ }^{\circ}\text{C}$ ;  $C_{bus} = 100\text{ pF}$ ;  $R_{bus} = 40\text{ }\Omega\text{ to }55\text{ }\Omega$  unless otherwise specified. All voltages are defined with respect to ground; positive currents flow into the IC.

| Symbol                        | Parameter  | Conditions   | Min | Typ | Max   | Unit    |
|-------------------------------|--|--|-----|-----|-------|---------|
| <b>Pin RXD</b>                |  |  |     |     |       |         |
| $t_r$                         | rise time  | $C_{RXD} = 15\text{ pF}$ ; 20 % to 80 %  | -   | -   | 9     | ns      |
|                               |  | $C_{RXD} = 25\text{ pF}$ ; 20 % to 80 %  | -   | -   | 10.75 |         |
| $t_f$                         | fall time  | $C_{RXD} = 15\text{ pF}$ ; 80 % to 20 %  | -   | -   | 9     | ns      |
|                               |  | $C_{RXD} = 25\text{ pF}$ ; 80 % to 20 %  | -   | -   | 10.75 |         |
| $t_{(r+f)}$                   | sum of rise and fall time                            | $C_{RXD} = 15\text{ pF}$ ; 20 % to 80 % and 80 % to 20 %   | -   | -   | 13    | ns      |
|                               |  | $C_{RXD} = 25\text{ pF}$ ; 20 % to 80 % and 80 % to 20 %   | -   | -   | 16.5  | ns      |
|                               |  | $C_{RXD} = 10\text{ pF}$ load at end of $50\text{ }\Omega$ $\mu$ strip with 1 ns delay; 20 % to 80 % and 80 % to 20 %; simulation only | -   | -   | 16.5  | ns      |
| $\Delta t_{(r-f)}$            | difference between rise and fall time                | $C_{RXD} = 15\text{ pF}$ ; 20 % to 80 %  | -5  | -   | +5    | ns      |
|                               |  | $C_{RXD} = 25\text{ pF}$ ; 20 % to 80 %  | -5  | -   | +5    | ns      |
|                               |  | $C_{RXD} = 10\text{ pF}$ load at end of $50\text{ }\Omega$ $\mu$ strip with 1 ns delay; 20 % to 80 % and 80 % to 20 %; simulation only | -5  | -   | +5    | ns      |
| <b>WAKE symbol detection</b>  |  |  |     |     |       |         |
| $t_{det(wake)DATA\_0}$        | DATA_0 wake-up detection time                        | Standby or Sleep mode;<br>$-10\text{ V} \leq V_{cm} \leq +15\text{ V}$   | 1   | -   | 4     | $\mu$ s |
| $t_{det(wake)idle}$           | idle wake-up detection time                          |  | 1   | -   | 4     | $\mu$ s |
| $t_{det(wake)tot}$            | total wake-up detection time                         |  | 50  | -   | 115   | $\mu$ s |
| $t_{sup(int)wake}$            | wake-up interruption suppression time                |  | [4] | 130 | -     | 1000    |
| <b>Reaction time</b>          |  |  |     |     |       |         |
| $t_{d(wakedet-INHH)}$         | delay time from wake-up detection to INH HIGH        | low-power mode;<br>$R_{L(INH-GND)} = 100\text{ k}\Omega$ ;<br>$V_{INH} = 2\text{ V}$   | -   | -   | 35    | $\mu$ s |
| $t_{d(event-ERRNL)}$          | delay time from event detection to ERRN LOW          | low-power mode   | -   | -   | 10    | $\mu$ s |
| $t_{d(wakedet-RXDL)}$         | delay time from wake-up detection to RXD LOW         | low-power mode   | -   | -   | 10    | $\mu$ s |
| $t_{d(STBNX-moch)}$           | delay time from STBN changing to mode change         |  | -   | -   | 100   | $\mu$ s |
| $t_{d(ENX-moch)}$             | delay time from EN changing to mode change           |  | -   | -   | 100   | $\mu$ s |
| <b>Undervoltage detection</b> |  |  |     |     |       |         |
| $t_{det(uv)(VCC)}$            | undervoltage detection time on pin $V_{CC}$          | $V_{CC} = 4.35\text{ V}$   | 5   | -   | 100   | $\mu$ s |
| $t_{to(uvd)(VCC)}$            | undervoltage detection time-out time on pin $V_{CC}$ |  | 100 | -   | 670   | ms      |
| $t_{rec(uv)(VCC)}$            | undervoltage recovery time on pin $V_{CC}$           | $V_{CC} = 4.85\text{ V}$   | 5   | -   | 100   | $\mu$ s |
| $t_{to(uvr)(VCC)}$            | undervoltage recovery time-out time on pin $V_{CC}$  |  | 1   | -   | 5.2   | ms      |

**Table 15. Dynamic characteristics ...continued**

All parameters are guaranteed for  $V_{BAT} = 4.45\text{ V to }60\text{ V}$ ;  $V_{CC} = 4.45\text{ V to }5.25\text{ V}$ ;  $V_{IO} = 2.55\text{ V to }5.25\text{ V}$ ;  $T_{vj} = -40\text{ °C to }+150\text{ °C}$ ;  $C_{bus} = 100\text{ pF}$ ;  $R_{bus} = 40\text{ }\Omega\text{ to }55\text{ }\Omega$  unless otherwise specified. All voltages are defined with respect to ground; positive currents flow into the IC.

| Symbol                     | Parameter  | Conditions  | Min               | Typ | Max | Unit          |
|----------------------------|--|---|-------------------|-----|-----|---------------|
| $t_{det(uv)}(V_{IO})$      | undervoltage detection time on pin $V_{IO}$          | $V_{IO} = 2.45\text{ V}$  | 5                 | -   | 100 | $\mu\text{s}$ |
| $t_{to(ugd)}(V_{IO})$      | undervoltage detection time-out time on pin $V_{IO}$ |   | 100               | -   | 670 | ms            |
| $t_{rec(uv)}(V_{IO})$      | undervoltage recovery time on pin $V_{IO}$           | $V_{IO} = 2.9\text{ V}$   | 5                 | -   | 100 | $\mu\text{s}$ |
| $t_{to(uvr)}(V_{IO})$      | undervoltage recovery time-out time on pin $V_{IO}$  |   | 1                 | -   | 5.2 | ms            |
| $t_{det(uv)}(V_{BAT})$     | undervoltage detection time on pin $V_{BAT}$         | $V_{BAT} = 4.35\text{ V}$   | 5                 | -   | 100 | $\mu\text{s}$ |
| $t_{rec(uv)}(V_{BAT})$     | undervoltage recovery time on pin $V_{BAT}$          | $V_{BAT} = 4.85\text{ V}$   | 5                 | -   | 100 | $\mu\text{s}$ |
| $t_{to(uvr)}(V_{BAT})$     | undervoltage recovery time-out time on pin $V_{BAT}$ |   | 1                 | -   | 5.2 | ms            |
| <b>Activity detection</b>  |  |   |                   |     |     |               |
| $t_{det(act)}(bus)$        | activity detection time on bus pins                  | $V_{dif}: 0\text{ mV} \rightarrow 400\text{ mV}$ ;<br>$V_{cm} = 2.5\text{ V}$ ;               | 100               | -   | 200 | ns            |
| $t_{det(idle)}(bus)$       | idle detection time on bus pins                      | $V_{dif}: 400\text{ mV} \rightarrow 0\text{ mV}$ ;<br>$V_{cm} = 2.5\text{ V}$ ;               | 50                | -   | 200 | ns            |
| $\Delta t_{det(act-idle)}$ | difference between active and idle detection time    | $V_{cm} = 2.5\text{ V}$   | -75               | -   | +75 | ns            |
| <b>Mode control pins</b>   |  |   |                   |     |     |               |
| $t_d(STBN-RXD)$            | STBN to RXD delay time                               | STBN HIGH to RXD HIGH;<br>remote or local wake-up<br>source flag set                          | 3                 | -   | 12  | $\mu\text{s}$ |
| $t_{ftr}(STBN)$            | filter time on pin STBN                              | rising and falling edges  | 3                 | -   | 10  | $\mu\text{s}$ |
| $t_d(STBN-stb)$            | delay time from STBN to standby mode                 | STBN LOW to Standby<br>mode; Receive-only mode  | <a href="#">5</a> | -   | 10  | $\mu\text{s}$ |
| $t_h(gotosleep)$           | go-to-sleep hold time                                |   | 20                | 35  | 50  | $\mu\text{s}$ |
| <b>Status register</b>     |  |   |                   |     |     |               |
| $t_{det}(EN)$              | detection time on pin EN                             | for mode control  | 5                 | -   | 20  | $\mu\text{s}$ |
| $T_{clk}(EN)$              | clock period on pin EN                               | EN signal used as clock for<br>reading status bits; see<br><a href="#">Figure 8</a>           | 1                 | -   | 5   | $\mu\text{s}$ |
| $t_d(EN-ERRN)$             | delay time from EN to ERRN                           | when reading status bits; see<br><a href="#">Figure 8</a>                                     | -                 | -   | 0.5 | $\mu\text{s}$ |
| <b>Pin WAKE</b>            |  |   |                   |     |     |               |
| $t_{ftr}(WAKE)$            | filter time on pin WAKE                              | low-power modes; falling<br>edge on pin WAKE;<br>$5.5\text{ V} \leq V_{BAT} \leq 27\text{ V}$ | 2.9               | -   | 100 | $\mu\text{s}$ |
|                            |  | low-power modes; falling<br>edge on pin WAKE;<br>$27\text{ V} \leq V_{BAT} \leq 60\text{ V}$  | 2.9               | -   | 175 | $\mu\text{s}$ |

**Table 15. Dynamic characteristics ...continued**

All parameters are guaranteed for  $V_{BAT} = 4.45\text{ V to }60\text{ V}$ ;  $V_{CC} = 4.45\text{ V to }5.25\text{ V}$ ;  $V_{IO} = 2.55\text{ V to }5.25\text{ V}$ ;  $T_{vj} = -40\text{ }^{\circ}\text{C to }+150\text{ }^{\circ}\text{C}$ ;  $C_{bus} = 100\text{ pF}$ ;  $R_{bus} = 40\text{ }\Omega\text{ to }55\text{ }\Omega$  unless otherwise specified. All voltages are defined with respect to ground; positive currents flow into the IC.

| Symbol                | Parameter                             | Conditions   | Min        | Typ | Max  | Unit          |
|-----------------------|---------------------------------------|--|------------|-----|------|---------------|
| <b>Miscellaneous</b>  |                                       |  |            |     |      |               |
| $t_{detCL}(TXEN)$     | TXEN clamp detection time             |  | 650        | -   | 2600 | $\mu\text{s}$ |
| $t_{d(busact-RXDL)}$  | delay time from bus active to RXD LOW | Normal mode; $V_{cm} = 2.5\text{ V}$ ; $C_{RXD} = 25\text{ pF}$ ; see <a href="#">Figure 9</a> | [6]<br>[7] | 100 | -    | 275 ns        |
| $t_{d(busidle-RXDH)}$ | delay time from bus idle to RXD HIGH  | Normal mode; $V_{cm} = 2.5\text{ V}$ ; $C_{RXD} = 25\text{ pF}$ ; see <a href="#">Figure 9</a> | [6]<br>[8] | 100 | -    | 275 ns        |

- [1] Values also guaranteed when the signal on TXD is constant for between 100 ns and 4400 ns before the first edge.
- [2] Sum of rise and fall times on TXD (20 % to 80 % on  $V_{IO}$ ) is 9 ns (max).
- [3] Guaranteed for  $V_{bus(dif)} = \pm 300\text{ mV}$  and  $V_{bus(dif)} = \pm 150\text{ mV}$ ;  $V_{bus(dif)}$  is the differential bus voltage  $V_{BP} - V_{BM}$ .
- [4] The minimum value is guaranteed when the phase that was interrupted was present continuously for at least 870 ns.
- [5] The same parameter is guaranteed by design for the transition from Normal to Go-to-sleep mode.
- [6] Not tested in production; guaranteed by design.
- [7]  $t_{d(busact-RXDL)} = t_{d(bus-RXD)} + t_{det(act)(bus)}$ .
- [8]  $t_{d(busidle-RXDH)} = t_{d(bus-RXD)} + t_{det(idle)(bus)}$ .

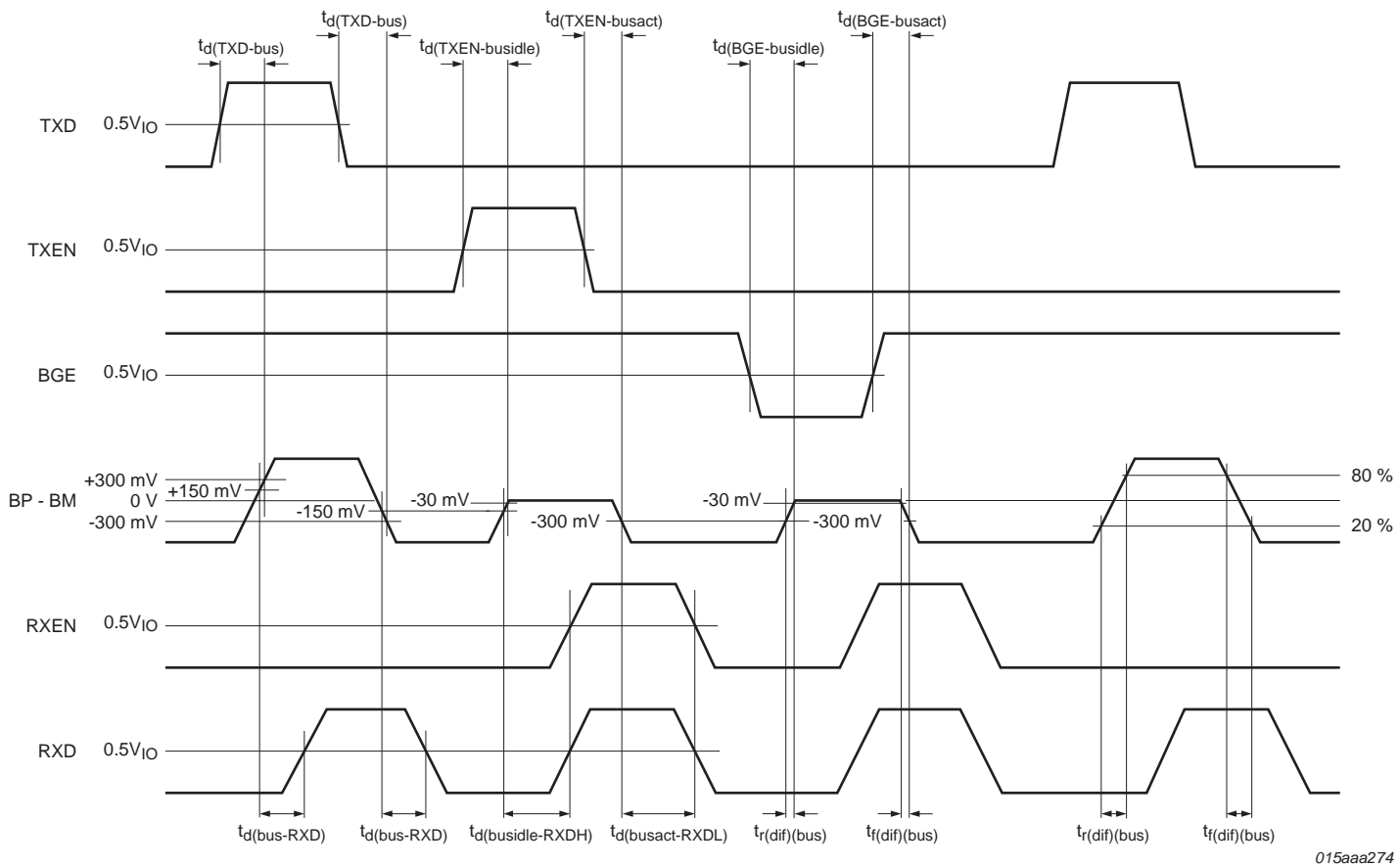
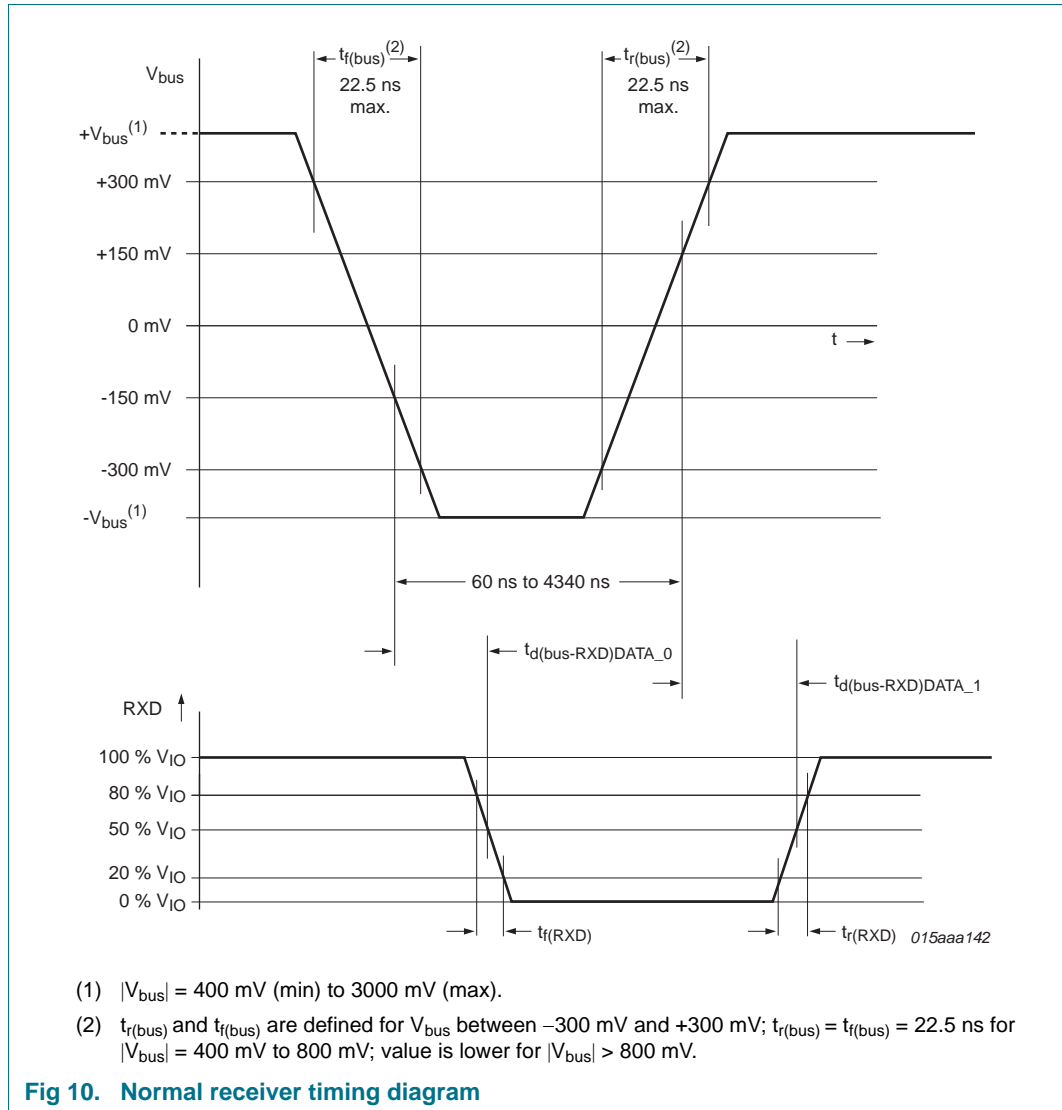


Fig 9. Detailed timing diagram





## 12. Application information

Further information on the application of the TJA1081G can be found in NXP application hints *AH102 TJA1081B/TJA1081G FlexRay node transceiver* ([Ref. 5](#)).

### 13. Test information

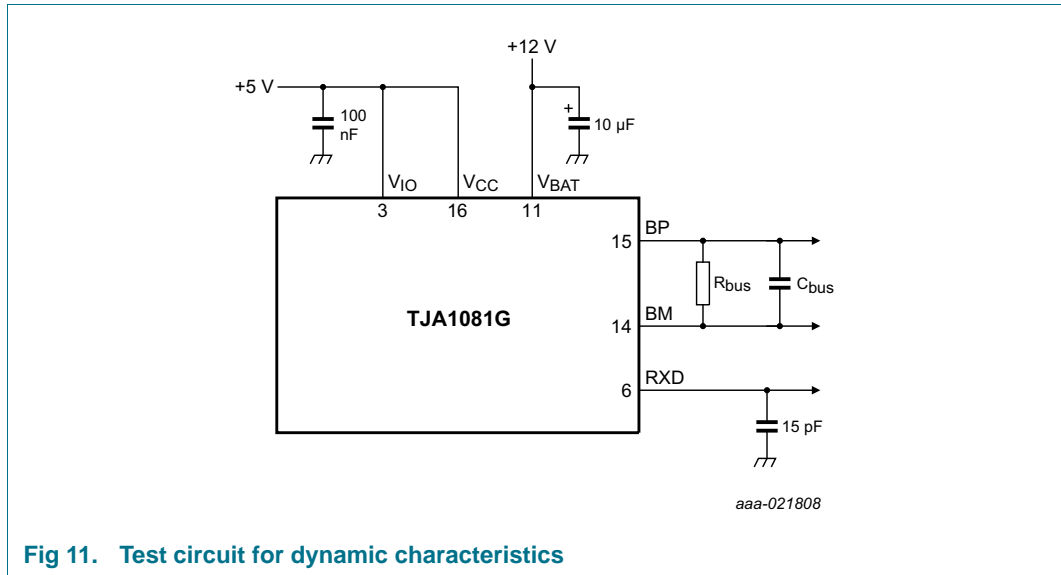


Fig 11. Test circuit for dynamic characteristics

#### 13.1 Quality information

This product has been qualified in accordance with the Automotive Electronics Council (AEC) standard Q100 Rev-G - *Failure mechanism based stress test qualification for integrated circuits*, and is suitable for use in automotive applications.

### 14. Package outline

SSOP16: plastic shrink small outline package; 16 leads; body width 5.3 mm

SOT338-1

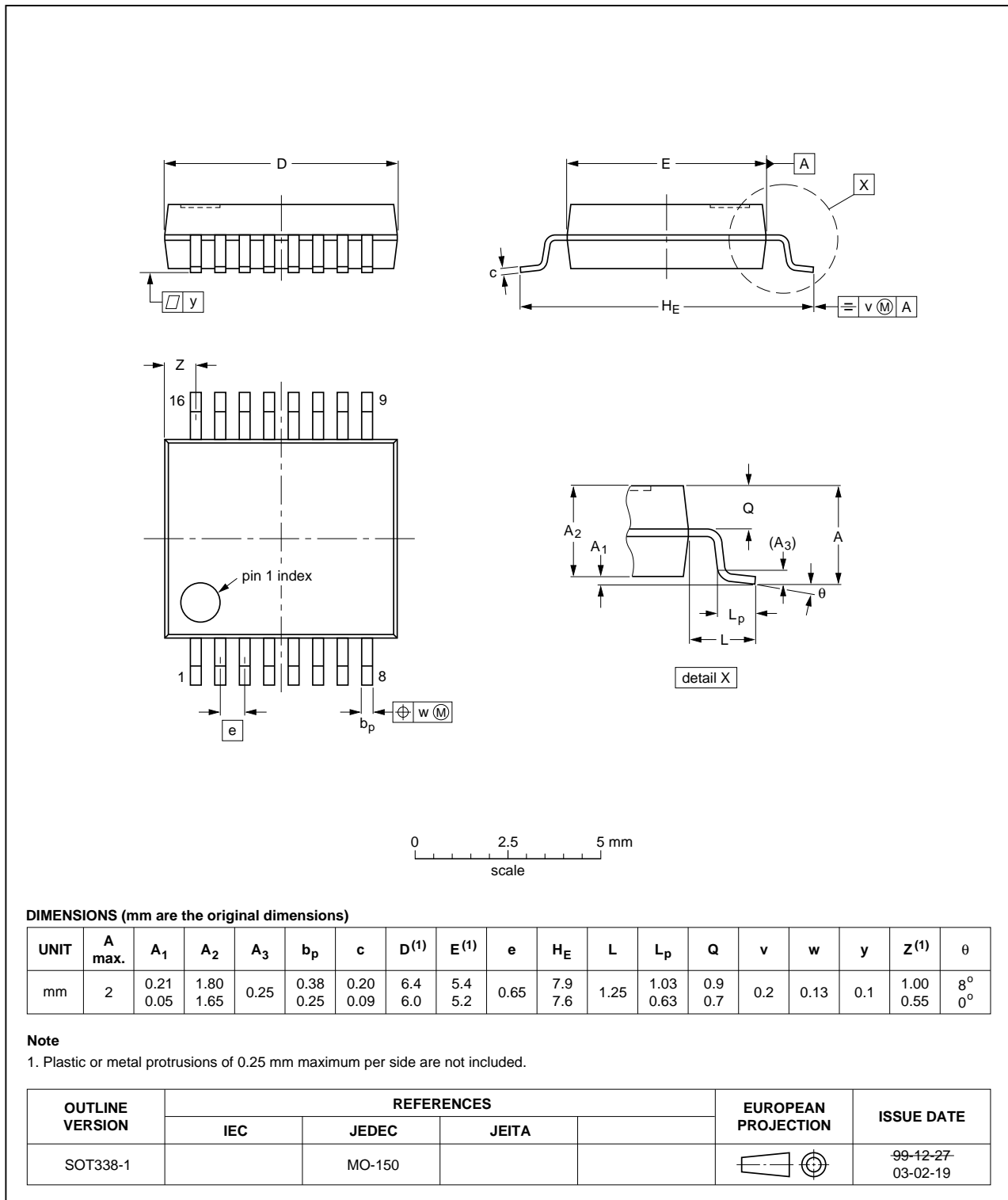


Fig 12. Package outline SOT338-1 (SSOP16)

## 15. Soldering of SMD packages

This text provides a very brief insight into a complex technology. A more in-depth account of soldering ICs can be found in Application Note *AN10365 "Surface mount reflow soldering description"*.

### 15.1 Introduction to soldering

Soldering is one of the most common methods through which packages are attached to Printed Circuit Boards (PCBs), to form electrical circuits. The soldered joint provides both the mechanical and the electrical connection. There is no single soldering method that is ideal for all IC packages. Wave soldering is often preferred when through-hole and Surface Mount Devices (SMDs) are mixed on one printed wiring board; however, it is not suitable for fine pitch SMDs. Reflow soldering is ideal for the small pitches and high densities that come with increased miniaturization.

### 15.2 Wave and reflow soldering

Wave soldering is a joining technology in which the joints are made by solder coming from a standing wave of liquid solder. The wave soldering process is suitable for the following:

- Through-hole components
- Leaded or leadless SMDs, which are glued to the surface of the printed circuit board

Not all SMDs can be wave soldered. Packages with solder balls, and some leadless packages which have solder lands underneath the body, cannot be wave soldered. Also, leaded SMDs with leads having a pitch smaller than ~0.6 mm cannot be wave soldered, due to an increased probability of bridging.

The reflow soldering process involves applying solder paste to a board, followed by component placement and exposure to a temperature profile. Leaded packages, packages with solder balls, and leadless packages are all reflow solderable.

Key characteristics in both wave and reflow soldering are:

- Board specifications, including the board finish, solder masks and vias
- Package footprints, including solder thieves and orientation
- The moisture sensitivity level of the packages
- Package placement
- Inspection and repair
- Lead-free soldering versus SnPb soldering

### 15.3 Wave soldering

Key characteristics in wave soldering are:

- Process issues, such as application of adhesive and flux, clinching of leads, board transport, the solder wave parameters, and the time during which components are exposed to the wave
- Solder bath specifications, including temperature and impurities

### 15.4 Reflow soldering

Key characteristics in reflow soldering are:

- Lead-free versus SnPb soldering; note that a lead-free reflow process usually leads to higher minimum peak temperatures (see [Figure 13](#)) than a SnPb process, thus reducing the process window
- Solder paste printing issues including smearing, release, and adjusting the process window for a mix of large and small components on one board
- Reflow temperature profile; this profile includes preheat, reflow (in which the board is heated to the peak temperature) and cooling down. It is imperative that the peak temperature is high enough for the solder to make reliable solder joints (a solder paste characteristic). In addition, the peak temperature must be low enough that the packages and/or boards are not damaged. The peak temperature of the package depends on package thickness and volume and is classified in accordance with [Table 16](#) and [17](#)

**Table 16. SnPb eutectic process (from J-STD-020D)**

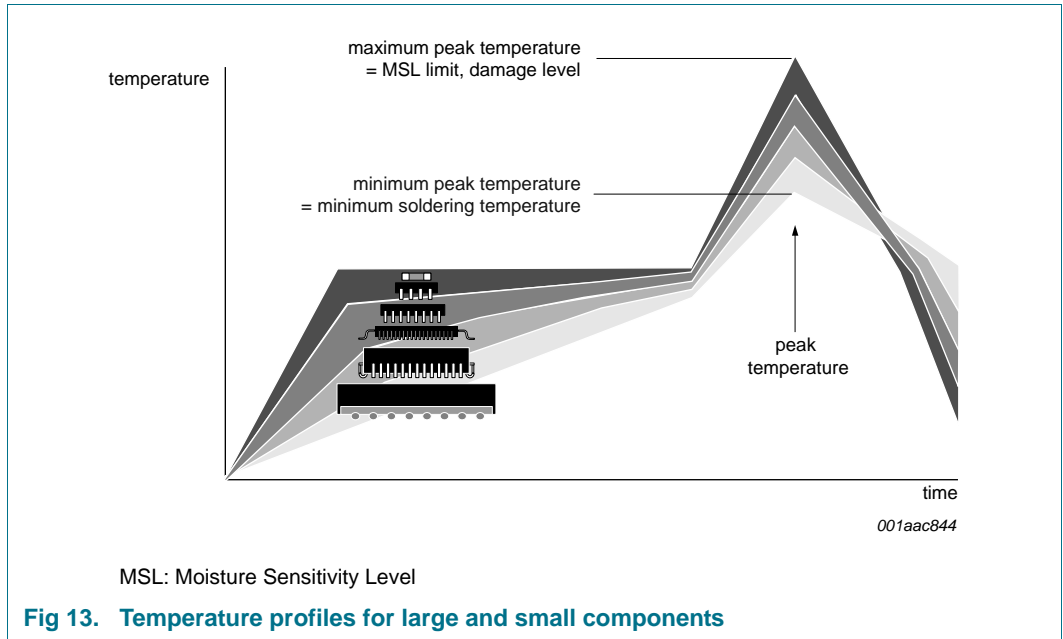
| Package thickness (mm) | Package reflow temperature (°C) |       |
|------------------------|---------------------------------|-------|
|                        | Volume (mm <sup>3</sup> )       |       |
|                        | < 350                           | ≥ 350 |
| < 2.5                  | 235                             | 220   |
| ≥ 2.5                  | 220                             | 220   |

**Table 17. Lead-free process (from J-STD-020D)**

| Package thickness (mm) | Package reflow temperature (°C) |             |        |
|------------------------|---------------------------------|-------------|--------|
|                        | Volume (mm <sup>3</sup> )       |             |        |
|                        | < 350                           | 350 to 2000 | > 2000 |
| < 1.6                  | 260                             | 260         | 260    |
| 1.6 to 2.5             | 260                             | 250         | 245    |
| > 2.5                  | 250                             | 245         | 245    |

Moisture sensitivity precautions, as indicated on the packing, must be respected at all times.

Studies have shown that small packages reach higher temperatures during reflow soldering, see [Figure 13](#).



For further information on temperature profiles, refer to Application Note AN10365 “Surface mount reflow soldering description”.

## 16. Appendix: EPL 3.0.1 to TJA1081G parameter conversion

**Table 18. EPL 3.0.1 to TJA1081G conversion**

This table maps the EPL 3.0.1 parameters names to those in the TJA1081G. Values are provided for reference only (see the characteristics tables for comprehensive listings of guaranteed parameter values).

| EPL 3.0.1                           |      |       |      | TJA1081G   |                |             |      |
|-------------------------------------|------|-------|------|--|----------------|-------------|------|
| Symbol                              | Min  | Max   | Unit | Symbol   | Min            | Max         | Unit |
| dBDRxAsym                           | -    | 5     | ns   | $\Delta t_{d(\text{bus-RXD})}$                             | -              | 5           | ns   |
| dBDRx10                             | -    | 75    | ns   | $t_{d(\text{bus-RXD})}$                                    | -              | 75          | ns   |
| dBDRx01                             | -    | 75    | ns   | $t_{d(\text{bus-RXD})}$                                    | -              | 75          | ns   |
| dBDRxai                             | 50   | 275   | ns   | $t_{d(\text{busidle-RXDH})}$                               | 100            | 275         | ns   |
| dBDRxia                             | 100  | 325   | ns   | $t_{d(\text{busact-RXDL})}$                                | 100            | 275         | ns   |
| dBDRxAsym                           | -    | 4     | ns   | $\Delta t_{d(\text{TXD-bus})}$                             | -              | 4           | ns   |
| dBDRx10                             | -    | 75    | ns   | $t_{d(\text{TXD-bus})}$                                    | -              | 60          | ns   |
| dBDRx01                             | -    | 75    | ns   | $t_{d(\text{TXD-bus})}$                                    | -              | 60          | ns   |
| dBDRxai                             | -    | 75    | ns   | $t_{d(\text{TXEN-busidle})}$                               | -              | 75          | ns   |
| dBDRxia                             | -    | 75    | ns   | $t_{d(\text{TXEN-busact})}$                                | -              | 75          | ns   |
| dBusTxai                            | -    | 30    | ns   | $t_{r(\text{dif})(\text{bus})(\text{DATA}_0\text{-idle})}$ | -              | 30          | ns   |
| dBusTxia                            | -    | 30    | ns   | $t_{f(\text{dif})(\text{bus})(\text{idle-DATA}_0)}$        | -              | 30          | ns   |
| dBusTx01                            | 6    | 18.75 | ns   | $t_{r(\text{dif})(\text{bus})}$                            | 6              | 18.75       | ns   |
| dBusTx10                            | 6    | 18.75 | ns   | $t_{f(\text{dif})(\text{bus})}$                            | 6              | 18.75       | ns   |
| uBDT <sub>xactive</sub>             | 600  | 2000  | mV   | $V_{OH(\text{dif})}$                                       | 600            | 2000        | mV   |
| uBDT <sub>xidle</sub>               | 0    | 30    | mV   | $V_{O(\text{idle})(\text{dif})}$                           | -25            | +25         | mV   |
| uVDIG-OUT-HIGH                      | 80   | 100   | %    | $V_{OH(\text{RXD})}$                                       | $V_{IO} - 0.4$ | $V_{IO}$    | V    |
| uVDIG-OUT-LOW                       | -    | 20    | %    | $V_{OL(\text{RXD})}$                                       | -              | 0.4         | V    |
| uVDIG-IN-HIGH                       | -    | 70    | %    | $V_{IH(\text{TXEN})}$                                      | $0.7V_{IO}$    | 5.5         | V    |
|                                     |      |       |      | $V_{IH(\text{EN})}$  | $0.7V_{IO}$    | 5.5         | V    |
|                                     |      |       |      | $V_{IH(\text{STBN})}$                                      | $0.7V_{IO}$    | 5.5         | V    |
|                                     |      |       |      | $V_{IH(\text{BGE})}$                                       | $0.7V_{IO}$    | 5.5         | V    |
| uVDIG-IN-LOW                        | 30   | -     | %    | $V_{IL(\text{TXEN})}$                                      | -0.3           | $0.3V_{IO}$ | V    |
|                                     |      |       |      | $V_{IL(\text{EN})}$  | -0.3           | $0.3V_{IO}$ | V    |
|                                     |      |       |      | $V_{IL(\text{STBN})}$                                      | -0.3           | $0.3V_{IO}$ | V    |
|                                     |      |       |      | $V_{IL(\text{BGE})}$                                       | -0.3           | $0.3V_{IO}$ | V    |
| uData0                              | -300 | -150  | mV   | $V_{IL(\text{dif})}$                                       | -300           | -150        | mV   |
| uData1                              | 150  | 300   | mV   | $V_{IH(\text{dif})}$                                       | 150            | 300         | mV   |
| uData1- uData0                      | -30  | +30   | mV   | $\Delta V_{i(\text{dif})(\text{H-L})}$                     | -30            | +30         | mV   |
| dBDAActivityDetection               | 100  | 250   | ns   | $t_{\text{det}(\text{act})(\text{bus})}$                   | 100            | 200         | ns   |
| dBDDIdleDetection                   | 50   | 200   | ns   | $t_{\text{det}(\text{idle})(\text{bus})}$                  | 50             | 200         | ns   |
| R <sub>CM1</sub> , R <sub>CM2</sub> | 10   | 40    | kΩ   | $R_{i(\text{BP})}$ , $R_{i(\text{BM})}$                    | 10             | 40          | kΩ   |
| uCM                                 | -10  | +15   | V    | $V_{\text{cm}}$ <sup>[1]</sup>                             | -10            | +15         | V    |
| iBM <sub>GNDShortMax</sub>          | -    | 60    | mA   | $ I_{O(\text{sc})(\text{BM})} $                            | -              | 60          | mA   |
| iBP <sub>GNDShortMax</sub>          | -    | 60    | mA   | $ I_{O(\text{sc})(\text{BP})} $                            | -              | 60          | mA   |
| iBM <sub>BAT48ShortMax</sub>        | -    | 72    | mA   | $ I_{O(\text{sc})(\text{BM})} $                            | -              | 60          | mA   |

**Table 18. EPL 3.0.1 to TJA1081G conversion ...continued**

This table maps the EPL 3.0.1 parameters names to those in the TJA1081G. Values are provided for reference only (see the characteristics tables for comprehensive listings of guaranteed parameter values).

| EPL 3.0.1   |      |      |      | TJA1081G  |      |       |      |
|---|------|------|------|---|------|-------|------|
| Symbol  | Min  | Max  | Unit | Symbol  | Min  | Max   | Unit |
| iBP <sub>BAT48ShortMax</sub>                          | -    | 72   | mA   | I <sub>O(sc)</sub> (BP)   | -    | 60    | mA   |
| iBM <sub>BAT27ShortMax</sub>                          | -    | 60   | mA   | I <sub>O(sc)</sub> (BM)   | -    | 60    | mA   |
| iBP <sub>BAT27ShortMax</sub>                          | -    | 60   | mA   | I <sub>O(sc)</sub> (BP)   | -    | 60    | mA   |
| uBias - Non-Low-Power                                 | 1800 | 3200 | mV   | V <sub>o(idle)</sub> (BP), V <sub>o(idle)</sub> (BM) <sup>[2]</sup> | 1800 | 3150  | mV   |
| uBias - Low-Power                                     | -200 | +200 | mV   | V <sub>o(idle)</sub> (BP), V <sub>o(idle)</sub> (BM) <sup>[3]</sup> | -0.1 | +0.1  | V    |
| dBDWakePulseFilter                                    | 1    | 500  | μs   | t <sub>fttr</sub> (WAKE)  | 2.9  | 100   | μs   |
| dWU <sub>0Detect</sub>                                | 1    | 4    | μs   | t <sub>det(wake)</sub> DATA_0                                       | 1    | 4     | μs   |
| dWU <sub>IdleDetect</sub>                             | 1    | 4    | μs   | t <sub>det(wake)</sub> idle   | 1    | 4     | μs   |
| dWU <sub>Timeout</sub>                                | 48   | 140  | μs   | t <sub>det(wake)</sub> tot  | 50   | 115   | μs   |
| uV <sub>BAT-WAKE</sub> (V <sub>CC</sub> implemented)  | -    | 7    | V    | V <sub>BAT</sub>  | 4.75 | 60    | V    |
| uBDUVV <sub>BAT</sub>                                 | 4    | 5.5  | V    | V <sub>uvd</sub> (VBAT)   | 4.45 | 4.715 | V    |
| uBDUVV <sub>CC</sub>                                  | 4    | -    | V    | V <sub>uvd</sub> (VCC)  | 4.45 | 4.72  | V    |
| dBDUVV <sub>CC</sub>                                  | -    | 1000 | ms   | t <sub>det(uv)</sub> (VCC)  | 5    | 100   | μs   |
|   |      |      |      | t <sub>to(uvd)</sub> (VCC)  | 100  | 670   | ms   |
| iBP <sub>Leak</sub>                                   | -    | 25   | μA   | I <sub>LI</sub> (BP)  | -5   | +5    | μA   |
| iBM <sub>Leak</sub>                                   | -    | 25   | μA   | I <sub>LI</sub> (BM)  | -5   | +5    | μA   |
| Functional class: BD voltage regulator control        |      |      |      | implemented; see <a href="#">Section 2.5</a>                        |      |       |      |
| Functional class: Bus Driver logic level adaptation   |      |      |      | implemented; see <a href="#">Section 2.5</a>                        |      |       |      |
| Functional class: Bus Driver - Bus guardian interface |      |      |      | implemented; see <a href="#">Section 2.5</a>                        |      |       |      |
| Device qualification according to AEC-Q100 (Rev. F)   |      |      |      | see <a href="#">Section 2.1</a>                                     |      |       |      |
| T <sub>AMB_Class1</sub>                               | -40  | +125 | °C   | T <sub>amb</sub>  | -40  | +125  | °C   |
| dBDTxD <sub>M</sub>                                   | -50  | +50  | ns   | Δt <sub>d</sub> (TXEN-bus)  | -50  | +50   | μs   |
| iBM <sub>-5VshortMax</sub>                            | -    | 60   | mA   | I <sub>O(sc)</sub> (BM)   | -    | 60    | mA   |
| iBP <sub>-5VshortMax</sub>                            | -    | 60   | mA   | I <sub>O(sc)</sub> (BP)   | -    | 60    | mA   |
| iBM <sub>BPSshortMax</sub>                            | -    | 60   | mA   | I <sub>O(sc)</sub> (BP-BM)  | -    | 60    | mA   |
| iBP <sub>BMSshortMax</sub>                            | -    | 60   | mA   | I <sub>O(sc)</sub> (BM-BP)  | -    | 60    | mA   |
| iBM <sub>BAT60ShortMax</sub>                          | -    | 90   | mA   | I <sub>O(sc)</sub> (BM)   | -    | 60    | mA   |
| iBP <sub>BAT60ShortMax</sub>                          | -    | 90   | mA   | I <sub>O(sc)</sub> (BP)   | -    | 60    | mA   |
| dBDUVV <sub>BAT</sub>                                 | -    | 1000 | ms   | t <sub>det(uv)</sub> (VBAT)   | 5    | 100   | μs   |
| uUV <sub>IO</sub>                                     | 2    | -    | V    | V <sub>uvd</sub> (VIO)  | 2.55 | 2.765 | V    |
| dBDUVV <sub>IO</sub>                                  | -    | 1000 | ms   | t <sub>det(uv)</sub> (VIO)  | 5    | 100   | μs   |
|   |      |      |      | t <sub>to(uvd)</sub> (VIO)  | 100  | 670   | ms   |
| dBDWakeupReaction <sub>local</sub>                    | -    | 100  | μs   | t <sub>d(wakedet-INHH)</sub>  | -    | 35    | μs   |
|   |      |      |      | t <sub>d(event-ERRNL)</sub>   | -    | 10    | μs   |
|   |      |      |      | t <sub>d(wakedet-RXDL)</sub>  | -    | 10    | μs   |
| dBDWakeupReaction <sub>remote</sub>                   | -    | 100  | μs   | t <sub>d(wakedet-INHH)</sub>  | -    | 35    | μs   |
|   |      |      |      | t <sub>d(event-ERRNL)</sub>   | -    | 10    | μs   |
|   |      |      |      | t <sub>d(wakedet-RXDL)</sub>  | -    | 10    | μs   |



**Table 18. EPL 3.0.1 to TJA1081G conversion ...continued**

This table maps the EPL 3.0.1 parameters names to those in the TJA1081G. Values are provided for reference only (see the characteristics tables for comprehensive listings of guaranteed parameter values).

| EPL 3.0.1   |                |      |      | TJA1081G   |                           |                            |      |   |     |    |
|---|----------------|------|------|--|---------------------------|----------------------------|------|---|-----|----|
| Symbol  | Min            | Max  | Unit | Symbol   | Min                       | Max                        | Unit |   |     |    |
| dBDTxActiveMax  | 650            | 2600 | μs   | t <sub>detCL</sub> (TXEN)  | 650                       | 2600                       | μs   |   |     |    |
| dBDMoDeChange   | -              | 100  | μs   | t <sub>d</sub> (STBNX-moch)  | -                         | 100                        | μs   |   |     |    |
|   |                |      |      | t <sub>d</sub> (ENX-moch)  |                           |                            |      | - | 100 | μs |
| dReactionTime <sub>ERRN</sub>   | -              | 100  | μs   | t <sub>d</sub> (event-ERRNL)   | -                         | 10                         | μs   |   |     |    |
| uINH1 <sub>Not_Sleep</sub>  | uVBAT<br>- 1 V | -    | V    | V <sub>OH</sub> (INH)  | V <sub>BAT</sub> -<br>0.8 | V <sub>BAT</sub>           | V    |   |     |    |
| iINH1 <sub>Leak</sub>   | -              | 10   | μA   | I <sub>L</sub> (INH)   | -5                        | +5                         | μA   |   |     |    |
| uData0_LP   | -400           | -100 | mV   | V <sub>IL</sub> (dif) (pins BP and BM)                               | -400                      | -100                       | mV   |   |     |    |
| dWU <sub>Interrupt</sub>  | 0.13           | 1    | μs   | t <sub>sup</sub> (int)wake   | 130                       | 1000                       | ns   |   |     |    |
| uBDLogic_1  | -              | 60   | %    | V <sub>IH</sub> (TXD)  | 0.6V <sub>IO</sub>        | V <sub>IO</sub> +<br>0.3 V | V    |   |     |    |
| uBDLogic_0  | 40             | -    | %    | V <sub>IL</sub> (TXD)  | -0.3                      | 0.4V <sub>IO</sub>         | V    |   |     |    |
| dBDRV <sub>CC</sub>   | -              | 10   | ms   | t <sub>rec</sub> (uv)(VCC)   | 5                         | 100                        | μs   |   |     |    |
|   |                |      |      | t <sub>to</sub> (uvr)(VCC)   |                           |                            |      | 1 | 5.2 | ms |
| dBDRV <sub>BAT</sub>  | -              | 10   | ms   | t <sub>rec</sub> (uv)(VBAT)  | 5                         | 100                        | μs   |   |     |    |
|   |                |      |      | t <sub>to</sub> (uvr)(VBAT)  |                           |                            |      | 1 | 5.2 | ms |
| dBDRV <sub>IO</sub>   | -              | 10   | ms   | t <sub>rec</sub> (uv)(VIO)   | 5                         | 100                        | μs   |   |     |    |
|   |                |      |      | t <sub>to</sub> (uvr)(VIO)   |                           |                            |      | 1 | 5.2 | ms |
| iBP <sub>LeakGND</sub>  | -              | 1600 | μA   | I <sub>LI</sub> (BP)   | -1600                     | +1600                      | μA   |   |     |    |
| iBM <sub>LeakGND</sub>  | -              | 1600 | μA   | I <sub>LI</sub> (BM)   | -1600                     | +1600                      | μA   |   |     |    |
| Functional class: Bus Driver Remote Wakeup  |                |      |      | implemented; see <a href="#">Section 2.5</a>                         |                           |                            |      |   |     |    |
| Functional class: Increased Voltage Amplitude Transmitter                                       |                |      |      | implemented; see <a href="#">Section 2.5</a>                         |                           |                            |      |   |     |    |
| uESD <sub>EXT</sub>   | 6              | -    | kV   | V <sub>ESD</sub>  : HBM on pins BP and BM to GND                     | 6                         | -                          | kV   |   |     |    |
|   |                |      |      | V <sub>ESD</sub>  : HBM on pins V <sub>BAT</sub> and WAKE to GND     |                           |                            |      | 4 | -   | kV |
| uESD <sub>INT</sub>   | 2              | -    | kV   | V <sub>ESD</sub>   (HBM on any other pin)                            | 2                         | -                          | kV   |   |     |    |
| uESD  | 6              | -    | kV   | IEC 61000-4-2 on pins BP, BM, V <sub>BAT</sub> and WAKE              | 6                         | -                          | kV   |   |     |    |
| dBDRxD <sub>R15</sub> + dBDRxD <sub>F15</sub>   | -              | 13   | ns   | t <sub>(r+f)</sub> (pin RXD; 15 pF load)                             | -                         | 13                         | ns   |   |     |    |
| dBDRxD <sub>R15</sub> - dBDRxD <sub>F15</sub>   | -              | 5    | ns   | Δt <sub>(r-f)</sub>   (pin RXD)                                      | -                         | 5                          | ns   |   |     |    |
| C <sub>BDTxD</sub>  | -              | 10   | pF   | C <sub>I</sub> (pin TXD)   | -                         | 10                         | pF   |   |     |    |
| dBDTxRxai   | -              | 325  | ns   | t <sub>d</sub> (TXENH-RXDH)  | -                         | 325                        | ns   |   |     |    |
| uVDIG-OUT-UV  | -              | 500  | mV   | V <sub>O</sub> (ERRN); with V <sub>IO</sub> < V <sub>uvd</sub> (VIO) | -                         | 500                        | mV   |   |     |    |
|   |                |      |      | V <sub>O</sub> (RXD); with V <sub>IO</sub> < V <sub>uvd</sub> (VIO)  |                           |                            |      | - | 500 | mV |
|   |                |      |      | V <sub>O</sub> (RXEN); with V <sub>IO</sub> < V <sub>uvd</sub> (VIO) |                           |                            |      | - | 500 | mV |
| valid operating modes when V <sub>BAT</sub> ≥ 5.5 V; V <sub>CC</sub> = nominal (if implemented) |                |      |      | Normal, Receive only, Standby, Sleep                                 |                           |                            |      |   |     |    |
| valid operating modes when V <sub>BAT</sub> ≥ 7 V; V <sub>CC</sub> = nominal                    |                |      |      | Normal, Receive only, Standby, Sleep                                 |                           |                            |      |   |     |    |

**Table 18. EPL 3.0.1 to TJA1081G conversion ...continued**

This table maps the EPL 3.0.1 parameters names to those in the TJA1081G. Values are provided for reference only (see the characteristics tables for comprehensive listings of guaranteed parameter values).

| EPL 3.0.1   |                  |      |      | TJA1081G  |                       |                 |      |
|---|------------------|------|------|---|-----------------------|-----------------|------|
| Symbol  | Min              | Max  | Unit | Symbol  | Min                   | Max             | Unit |
| uV <sub>DIG-OUT-OFF</sub>                             | product specific |      |      | V <sub>O(ERRN)</sub> <sup>[4]</sup>                               | -                     | 0.5             | V    |
|   |                  |      |      | V <sub>O(RXD)</sub> <sup>[4]</sup>                                | V <sub>IO</sub> - 0.5 | V <sub>IO</sub> | V    |
|   |                  |      |      | V <sub>O(RXEN)</sub> <sup>[4]</sup>                               | V <sub>IO</sub> - 0.5 | V <sub>IO</sub> | V    |
| R <sub>BDTransmitter</sub>                            | product-specific |      |      | Z <sub>o(eq)TX</sub>  | 35                    | 100             | Ω    |
| RxD signal sum of rise and fall time at TP4_CC        | -                | 16.5 | ns   | t <sub>(r+f)(RXD)</sub> (10 pF load on 50 Ω μstrip; simulated)    | -                     | 16.5            | ns   |
| uV <sub>BAT-WAKE</sub> (no V <sub>CC</sub> )          | -                | 5.5  | V    | V <sub>BAT</sub> (operating range)                                | 4.75                  | 60              | V    |
| dBDRxD <sub>R25</sub> + dBDRxD <sub>F25</sub>         | -                | 16.5 | ns   | t <sub>(r+f)(RXD)</sub> (25 pF load)                              | -                     | 16.5            | ns   |
| dBDRxD <sub>R25</sub> - dBDRxD <sub>F25</sub>         | -                | 5    | ns   | Δt <sub>(r-f)(RXD)</sub>  | -5                    | +5              | ns   |
| dBusTxDif   | -                | 3    | ns   | Δt <sub>(r-f)(dif)</sub> (on bus)                                 | -3                    | +3              | ns   |
| RxD signal difference of rise and fall time at TP4_CC | -                | 5    | ns   | Δt <sub>(r-f)(RXD)</sub>   (10 pF load on 50 Ω μstrip; simulated) | -                     | 5               | ns   |

- [1] V<sub>cm</sub> is the BP/BM common mode voltage (V<sub>BP</sub> + V<sub>BM</sub>/2) and is specified in conditions column for V<sub>IH(dif)</sub> and V<sub>IH(dif)</sub> for pins BP and BM; see Table 14. V<sub>cm</sub> is tested on a receiving bus driver with a transmitting bus driver that has a ground offset voltage in the range -12.5 V to +12.5 V and that transmits a 50/50 pattern.
- [2] Min: V<sub>o(idle)(BP)</sub> = V<sub>o(idle)(BM)</sub> = 0.4V<sub>CC</sub> = 0.4 × 4.5 V = 1800 mV; max value: V<sub>o(idle)(BP)</sub> = V<sub>o(idle)(BM)</sub> = 0.6V<sub>CC</sub> = 0.6 × 5.25 V = 3150 mV; the nominal voltage is 2500 mV.
- [3] The nominal voltage is 0 mV.
- [4] Power off.

## 17. Abbreviations

Table 19. Abbreviations

| Abbreviation | Description                   |
|--------------|-------------------------------|
| BSS          | Byte Start Sequence           |
| CDM          | Charged Device Model          |
| ECU          | Electronic Control Unit       |
| EMC          | ElectroMagnetic Compatibility |
| EME          | ElectroMagnetic Emission      |
| EMI          | ElectroMagnetic Immunity      |
| ESD          | ElectroStatic Discharge       |
| HBM          | Human Body Model              |
| MM           | Machine Model                 |
| TSS          | Transmission Start Sequence   |

## 18. References

- [1] **EPL** — FlexRay Communications System Electrical Physical Layer Specification Version 3.0.1, FlexRay Consortium
- [2] **ISO 17458-4:2013** — Road vehicles - FlexRay Communications System part 4: Electrical physical layer specification
- [3] **TJA1080A** — FlexRay transceiver data sheet, [www.nxp.com](http://www.nxp.com)
- [4] **TJA1081B** — FlexRay transceiver data sheet, [www.nxp.com](http://www.nxp.com)
- [5] **AH1102** — TJA1081B/TJA1081G FlexRay node transceiver application hints, available from NXP Semiconductors

## 19. Revision history

Table 20. Revision history

| Document ID  | Release date | Data sheet status  | Change notice | Supersedes |
|--------------|--------------|--------------------|---------------|------------|
| TJA1081G v.1 | 20161028     | Product data sheet | -             | -          |

## 20. Legal information

### 20.1 Data sheet status

| Document status <sup>[1][2]</sup> | Product status <sup>[3]</sup> | Definition  |
|-----------------------------------|-------------------------------|---|
| Objective [short] data sheet      | Development                   | This document contains data from the objective specification for product development. |
| Preliminary [short] data sheet    | Qualification                 | This document contains data from the preliminary specification.                       |
| Product [short] data sheet        | Production                    | This document contains the product specification.                                     |

[1] Please consult the most recently issued document before initiating or completing a design.

[2] The term 'short data sheet' is explained in section "Definitions".

[3] The product status of device(s) described in this document may have changed since this document was published and may differ in case of multiple devices. The latest product status information is available on the Internet at URL <http://www.nxp.com>.

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