

# HEF4069UB-Q100

Hex inverter

Rev. 2 — 9 September 2014

Product data sheet

## 1. General description

The HEF4069UB-Q100 is a general-purpose hex inverter. Each inverter has a single stage.

It operates over a recommended  $V_{DD}$  power supply range of 3 V to 15 V referenced to  $V_{SS}$  (usually ground). Unused inputs must be connected to  $V_{DD}$ ,  $V_{SS}$ , or another input.

This product has been qualified to the Automotive Electronics Council (AEC) standard Q100 (Grade 1) and is suitable for use in automotive applications.

## 2. Features and benefits

- Automotive product qualification in accordance with AEC-Q100 (Grade 1)
  - ◆ Specified from  $-40\text{ }^{\circ}\text{C}$  to  $+85\text{ }^{\circ}\text{C}$  and from  $-40\text{ }^{\circ}\text{C}$  to  $+125\text{ }^{\circ}\text{C}$
- Fully static operation
- 5 V, 10 V, and 15 V parametric ratings
- Standardized symmetrical output characteristics
- ESD protection:
  - ◆ MIL-STD-883, method 3015 exceeds 2000 V
  - ◆ HBM JESD22-A114F exceeds 2000 V
  - ◆ MM JESD22-A115-A exceeds 200 V ( $C = 200\text{ pF}$ ,  $R = 0\text{ }\Omega$ )
- Complies with JEDEC standard JESD 13-B

## 3. Applications

- Oscillator

## 4. Ordering information

**Table 1. Ordering information**

All types operate from  $-40\text{ }^{\circ}\text{C}$  to  $+125\text{ }^{\circ}\text{C}$ .

Type number	Package		
	Name	Description	Version
HEF4069UBT-Q100	SO14	plastic small outline package; 14 leads; body width 3.9 mm	SOT108-1
HEF4069UBTT-Q100	TSSOP14	plastic thin shrink small outline package; 14 leads; body width 4.4 mm	SOT402-1

## 5. Functional diagram

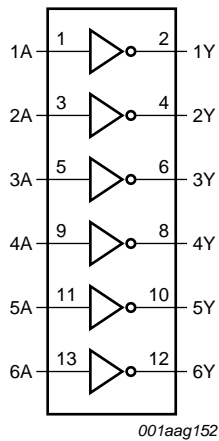


Fig 1. Functional diagram

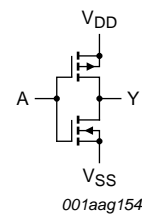


Fig 2. Schematic diagram (one inverter)

## 6. Pinning information

### 6.1 Pinning

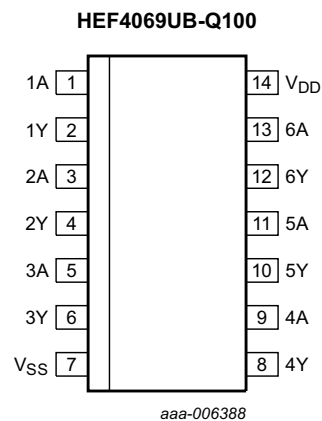


Fig 3. Pin configuration

### 6.2 Pin description

Table 2. Pin description

Symbol	Pin	Description
1A to 6A	1, 3, 5, 9, 11, 13	input
1Y to 6Y	2, 4, 6, 8, 10, 12	output
V <sub>SS</sub>	7	ground (0 V)
V <sub>DD</sub>	14	supply voltage

## 7. Limiting values

**Table 3. Limiting values**

In accordance with the Absolute Maximum Rating System (IEC 60134).

Symbol	Parameter	Conditions	Min	Max	Unit	
$V_{DD}$	supply voltage		-0.5	+18	V	
$I_{IK}$	input clamping current	$V_I < -0.5\text{ V}$ or $V_I > V_{DD} + 0.5\text{ V}$	-	$\pm 10$	mA	
$V_I$	input voltage		-0.5	$V_{DD} + 0.5$	V	
$I_{OK}$	output clamping current	$V_O < -0.5\text{ V}$ or $V_O > V_{DD} + 0.5\text{ V}$	-	$\pm 10$	mA	
$I_{I/O}$	input/output current		-	$\pm 10$	mA	
$I_{DD}$	supply current		-	50	mA	
$T_{stg}$	storage temperature		-65	+150	°C	
$T_{amb}$	ambient temperature		-40	+125	°C	
$P_{tot}$	total power dissipation	$T_{amb} = -40\text{ °C}$ to $+125\text{ °C}$				
		SO14	[1]	-	500	mW
		TSSOP14	[2]	-	500	mW
$P$	power dissipation	per output	-	100	mW	

[1] For SO14 packages: above  $T_{amb} = 70\text{ °C}$ ,  $P_{tot}$  derates linearly with 8 mW/K.

[2] For TSSOP14 packages: above  $T_{amb} = 60\text{ °C}$ ,  $P_{tot}$  derates linearly with 5.5 mW/K.

## 8. Recommended operating conditions

**Table 4. Recommended operating conditions**

Symbol	Parameter	Conditions	Min	Typ	Max	Unit
$V_{DD}$	supply voltage		3	-	15	V
$V_I$	input voltage		0	-	$V_{DD}$	V
$T_{amb}$	ambient temperature	in free air	-40	-	+125	°C

## 9. Static characteristics

**Table 5. Static characteristics**

$V_{SS} = 0\text{ V}$ ;  $V_I = V_{SS}$  or  $V_{DD}$ ; unless otherwise specified.

Symbol	Parameter	Conditions	$V_{DD}$	$T_{amb} = -40\text{ °C}$		$T_{amb} = +25\text{ °C}$		$T_{amb} = +85\text{ °C}$		$T_{amb} = +125\text{ °C}$		Unit
				Min	Max	Min	Max	Min	Max	Min	Max	
$V_{IH}$	HIGH-level input voltage	$ I_O  < 1\text{ }\mu\text{A}$	5 V	4	-	4	-	4	-	4	-	V
			10 V	8	-	8	-	8	-	8	-	V
			15 V	12.5	-	12.5	-	12.5	-	12.5	-	V
$V_{IL}$	LOW-level input voltage	$ I_O  < 1\text{ }\mu\text{A}$	5 V	-	1	-	1	-	1	-	1	V
			10 V	-	2	-	2	-	2	-	2	V
			15 V	-	2.5	-	2.5	-	2.5	-	2.5	V
$V_{OH}$	HIGH-level output voltage	$ I_O  < 1\text{ }\mu\text{A}$	5 V	4.95	-	4.95	-	4.95	-	4.95	-	V
			10 V	9.95	-	9.95	-	9.95	-	9.95	-	V
			15 V	14.95	-	14.95	-	14.95	-	14.95	-	V
$V_{OL}$	LOW-level output voltage	$ I_O  < 1\text{ }\mu\text{A}$	5 V	-	0.05	-	0.05	-	0.05	-	0.05	V
			10 V	-	0.05	-	0.05	-	0.05	-	0.05	V
			15 V	-	0.05	-	0.05	-	0.05	-	0.05	V
$I_{OH}$	HIGH-level output current	$V_O = 2.5\text{ V}$	5 V	-	-1.7	-	-1.4	-	-1.1	-	-1.1	mA
		$V_O = 4.6\text{ V}$	5 V	-	-0.64	-	-0.5	-	-0.36	-	-0.36	mA
		$V_O = 9.5\text{ V}$	10 V	-	-1.6	-	-1.3	-	-0.9	-	-0.9	mA
		$V_O = 13.5\text{ V}$	15 V	-	-4.2	-	-3.4	-	-2.4	-	-2.4	mA
$I_{OL}$	LOW-level output current	$V_O = 0.4\text{ V}$	5 V	0.64	-	0.5	-	0.36	-	0.36	-	mA
		$V_O = 0.5\text{ V}$	10 V	1.6	-	1.3	-	0.9	-	0.9	-	mA
		$V_O = 1.5\text{ V}$	15 V	4.2	-	3.4	-	2.4	-	2.4	-	mA
$I_I$	input leakage current		15 V	-	$\pm 0.1$	-	$\pm 0.1$	-	$\pm 1.0$	-	$\pm 1.0$	$\mu\text{A}$
$I_{DD}$	supply current	all valid input combinations; $I_O = 0\text{ A}$	5 V	-	0.25	-	0.25	-	7.5	-	7.5	$\mu\text{A}$
			10 V	-	0.5	-	0.5	-	15.0	-	15.0	$\mu\text{A}$
			15 V	-	1.0	-	1.0	-	30.0	-	30.0	$\mu\text{A}$
$C_I$	input capacitance	digital inputs		-	-	-	7.5	-	-	-	pF	

## 10. Dynamic characteristics

**Table 6. Dynamic characteristics**

$T_{amb} = 25\text{ °C}$ ; for waveforms see [Figure 4](#); for test circuit see [Figure 5](#).

Symbol	Parameter	Conditions	V <sub>DD</sub>	Extrapolation formula <sup>[1]</sup>	Min	Typ	Max	Unit
t <sub>PHL</sub>	HIGH to LOW propagation delay	nA to nY	5 V	$18\text{ ns} + (0.55\text{ ns/pF})C_L$	-	45	90	ns
			10 V	$9\text{ ns} + (0.23\text{ ns/pF})C_L$	-	20	40	ns
			15 V	$7\text{ ns} + (0.16\text{ ns/pF})C_L$	-	15	25	ns
t <sub>PLH</sub>	LOW to HIGH propagation delay	nA to nY	5 V	$13\text{ ns} + (0.55\text{ ns/pF})C_L$	-	40	80	ns
			10 V	$9\text{ ns} + (0.23\text{ ns/pF})C_L$	-	20	40	ns
			15 V	$7\text{ ns} + (0.16\text{ ns/pF})C_L$	-	15	30	ns
t <sub>THL</sub>	HIGH to LOW output transition time	output nY	5 V	$10\text{ ns} + (1.00\text{ ns/pF})C_L$	-	60	120	ns
			10 V	$9\text{ ns} + (0.42\text{ ns/pF})C_L$	-	30	60	ns
			15 V	$6\text{ ns} + (0.28\text{ ns/pF})C_L$	-	20	40	ns
t <sub>TLH</sub>	LOW to HIGH output transition time	output nY	5 V	$10\text{ ns} + (1.00\text{ ns/pF})C_L$	-	60	120	ns
			10 V	$9\text{ ns} + (0.42\text{ ns/pF})C_L$	-	30	60	ns
			15 V	$6\text{ ns} + (0.28\text{ ns/pF})C_L$	-	20	40	ns

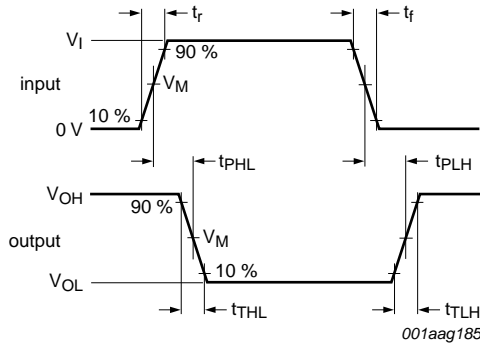
[1] The typical value of the propagation delay and output transition time can be calculated with the extrapolation formula ( $C_L$  in pF).

**Table 7. Dynamic power dissipation**

$V_{SS} = 0\text{ V}$ ;  $t_r = t_f \leq 20\text{ ns}$ ;  $T_{amb} = 25\text{ °C}$ .

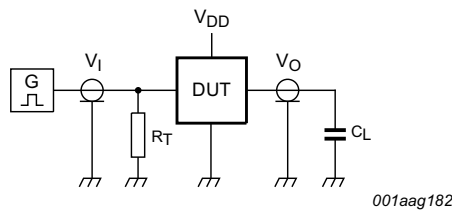
Symbol	Parameter	V <sub>DD</sub>	Typical formula	Where
P <sub>D</sub>	dynamic power dissipation	5 V	$P_D = 600 \times f_i + \Sigma(f_o \times C_L) \times V_{DD}^2\ (\mu\text{W})$	$f_i$ = input frequency in MHz; $f_o$ = output frequency in MHz; $C_L$ = output load capacitance in pF; $\Sigma(f_o \times C_L)$ = sum of the outputs; $V_{DD}$ = supply voltage in V.
		10 V	$P_D = 4000 \times f_i + \Sigma(f_o \times C_L) \times V_{DD}^2\ (\mu\text{W})$	
		15 V	$P_D = 22000 \times f_i + \Sigma(f_o \times C_L) \times V_{DD}^2\ (\mu\text{W})$	

11. Waveforms



Measurement points:  $V_M = 0.5V_{DD}$ .  
 Logic levels:  $V_{OL}$  and  $V_{OH}$  are typical output voltage levels that occur with the output load.

Fig 4. Propagation delay and transition times



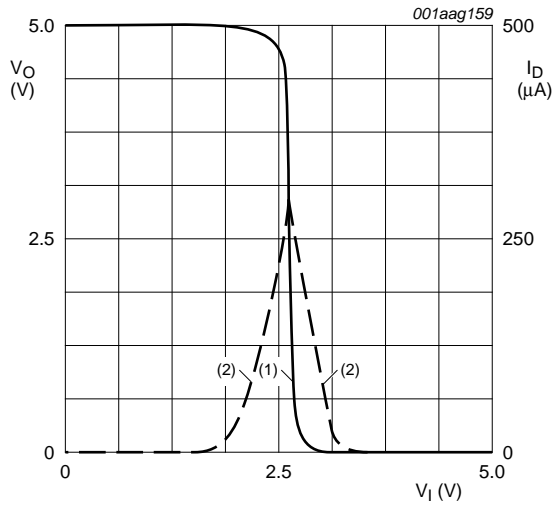
Definitions for test circuit:  
 $C_L$  = load capacitance including jig and probe capacitance;  
 $R_T$  = termination resistance should be equal to the output impedance  $Z_o$  of the pulse generator;  
 For test data, refer to [Table 8](#).

Fig 5. Test circuit for measuring switching times

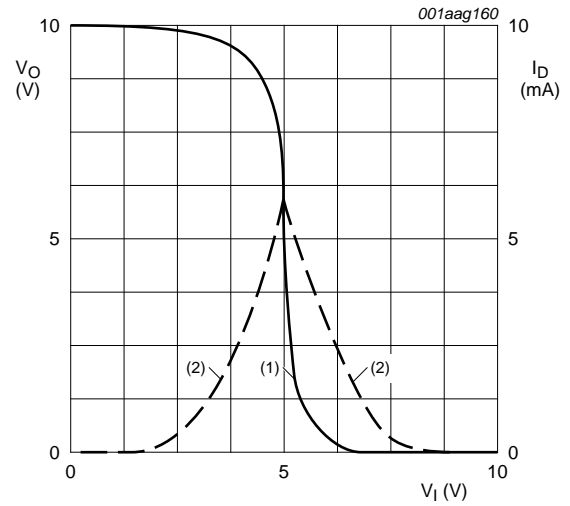
Table 8. Test data

Supply voltage	Input	Load
$V_{DD}$	$V_I$	$C_L$
5 V to 15 V	$V_{SS}$ or $V_{DD}$	50 pF
	$t_r, t_f$	$\leq 20$ ns

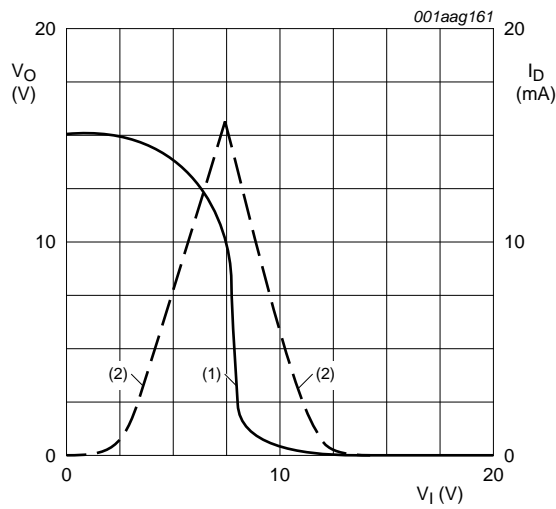
11.1 Transfer characteristics



a.  $V_{DD} = 5\text{ V}; I_O = 0\text{ A}$



b.  $V_{DD} = 10\text{ V}; I_O = 0\text{ A}$



c.  $V_{DD} = 15\text{ V}; I_O = 0\text{ A}$

- (1)  $V_O$  = output voltage.
- (2)  $I_D$  = drain current.

Fig 6. Typical transfer characteristics

## 12. Application information

Some examples of applications for the HEF4069UB-Q100.

[Figure 7](#) shows an astable relaxation oscillator using two HEF4069UB-Q100 inverters and 2 BAW62 diodes. The oscillation frequency is mainly determined by  $R1 \times C1$ , provided  $R1 \ll R2$  and  $R2 \times C2 \ll R1 \times C1$ .

The function of R2 is to minimize the influence of the forward voltage across the protection diodes on the frequency; C2 is a stray (parasitic) capacitance.

The period  $T_p$  is given by  $T_p = T_1 + T_2$ ,

where:

$$T_1 = R1C1 \ln \frac{V_{DD} + V_{ST}}{V_{ST}}$$

$$T_2 = R1C1 \ln \frac{2V_{DD} - V_{ST}}{V_{DD} - V_{ST}}$$

$V_{ST}$  = the signal threshold level of the inverter.

The period is fairly independent of  $V_{DD}$ ,  $V_{ST}$  and temperature. The duty factor, however, is influenced by  $V_{ST}$ .

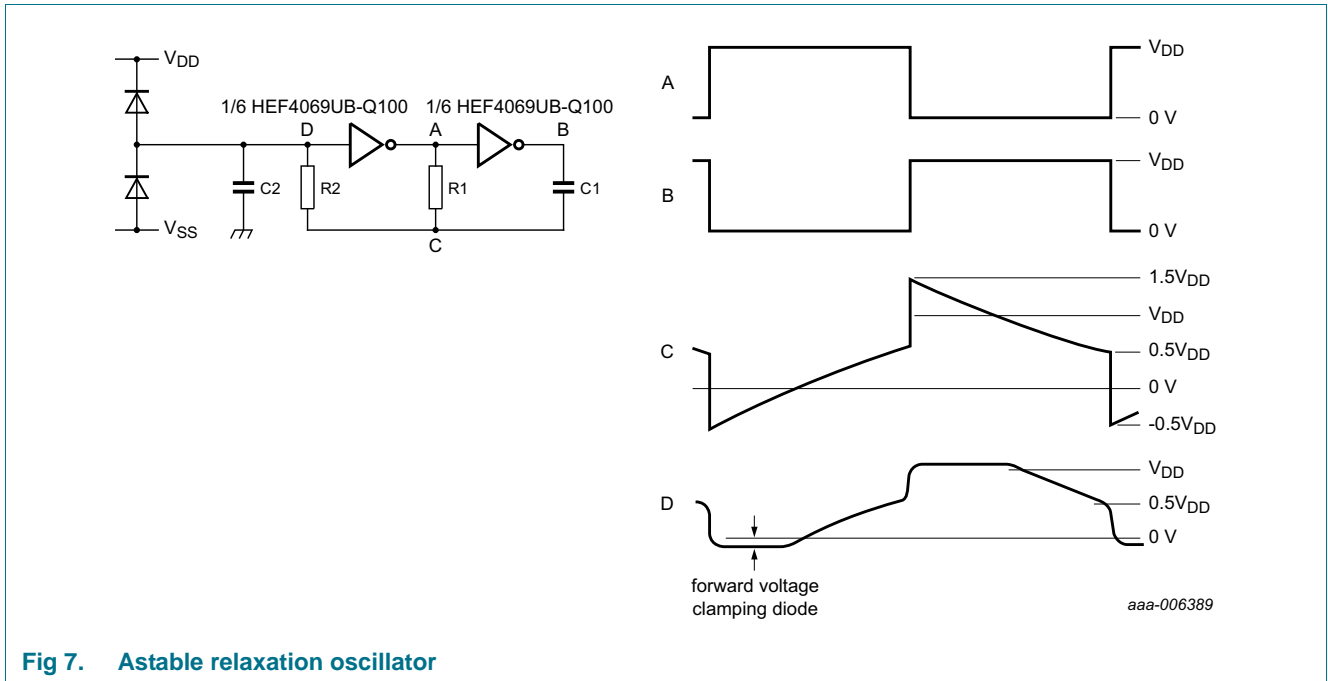
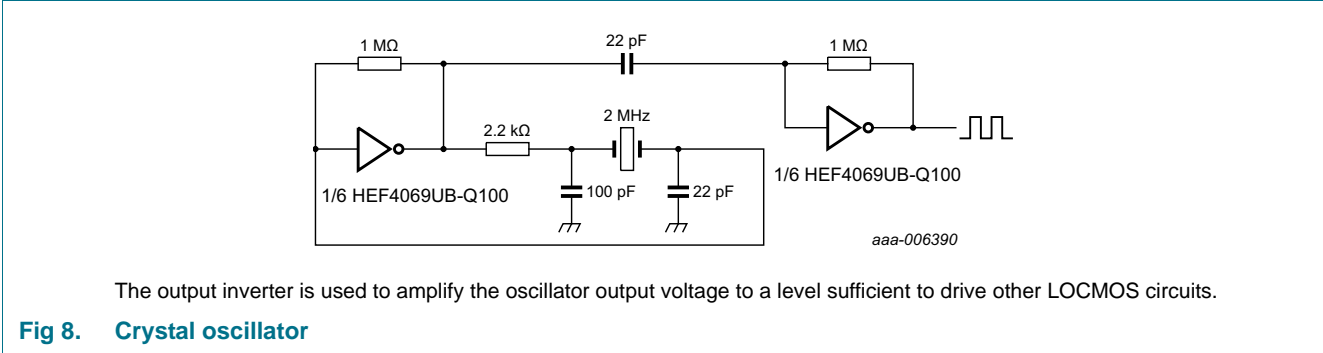


Fig 7. Astable relaxation oscillator



Figure 8 shows a crystal oscillator for frequencies up to 10 MHz using two HEF4069UB-Q100 inverters. The second inverter amplifies the oscillator output voltage to a level sufficient to drive other Local Oxidation CMOS (LOCMOS) circuits.



The output inverter is used to amplify the oscillator output voltage to a level sufficient to drive other LOCMOS circuits.

Fig 8. Crystal oscillator

Figure 9 and Figure 10 show voltage gain and supply current. Figure 11 shows the test set-up and an example of an analog amplifier using one HEF4069UB-Q100.

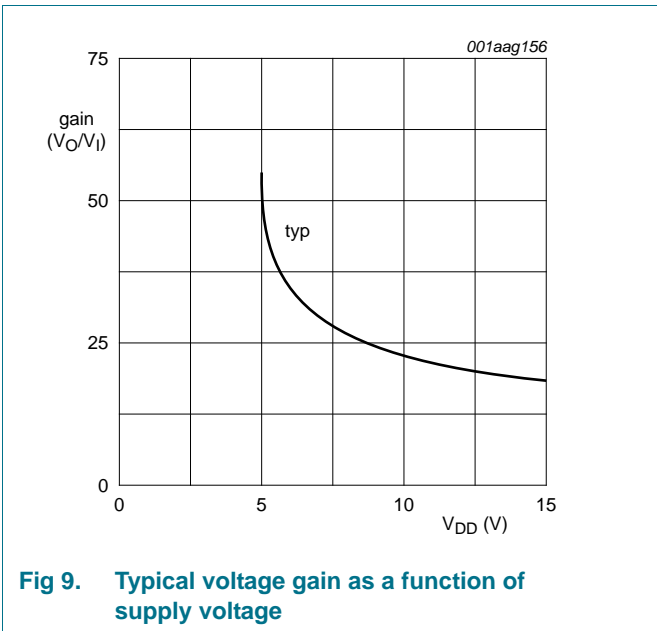


Fig 9. Typical voltage gain as a function of supply voltage

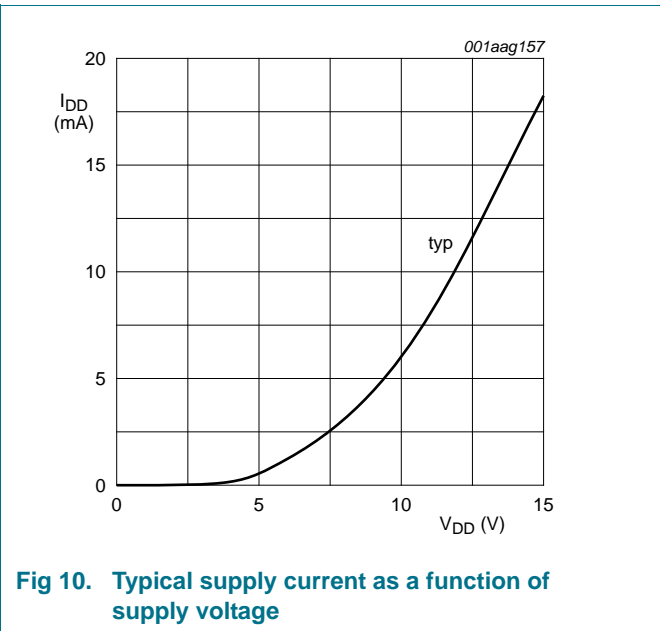


Fig 10. Typical supply current as a function of supply voltage

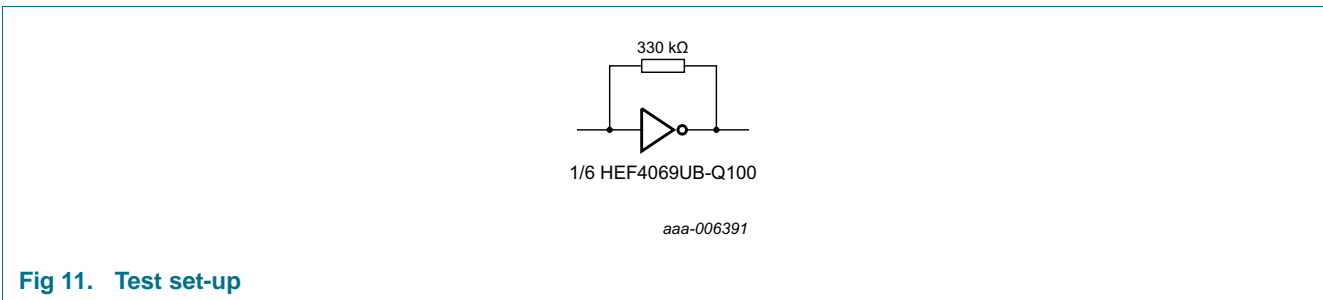
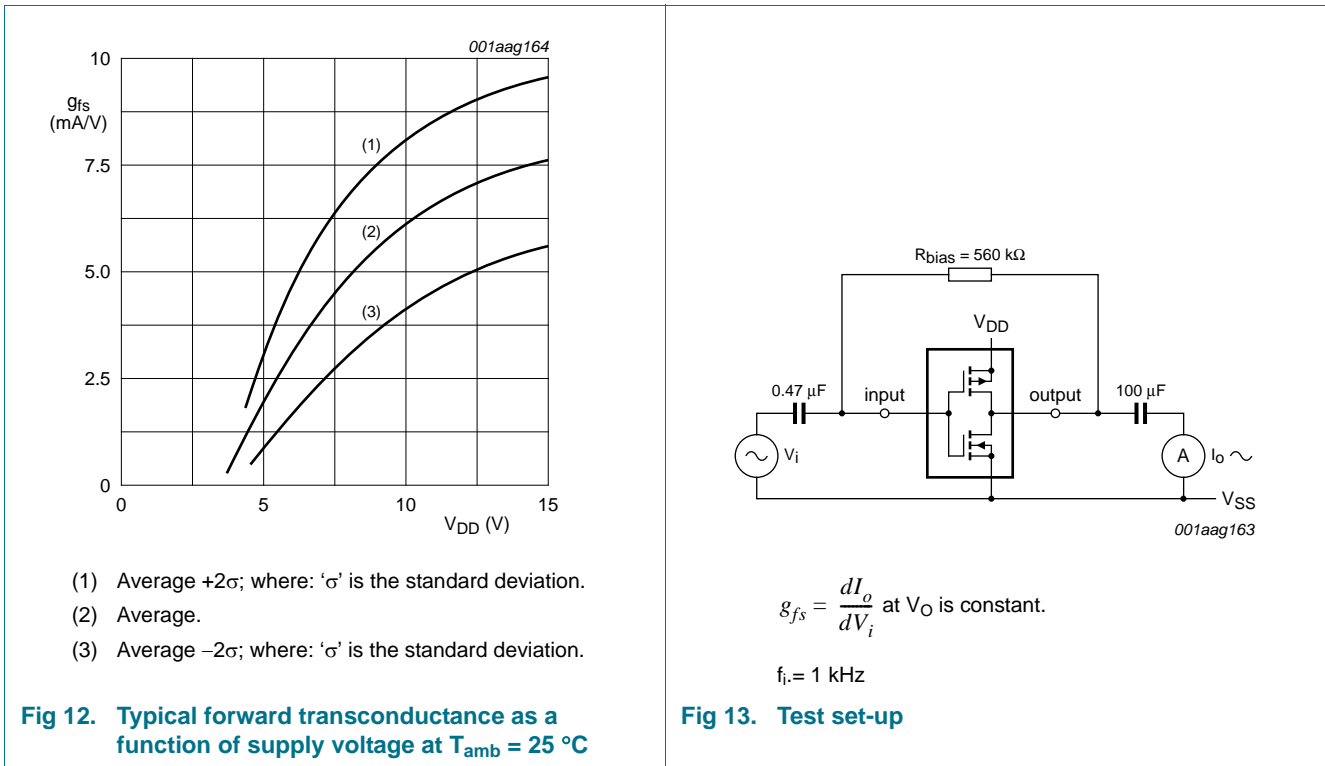


Fig 11. Test set-up

Figure 12 shows typical forward transconductance and Figure 13 shows the test set-up.



13. Package outline

SO14: plastic small outline package; 14 leads; body width 3.9 mm

SOT108-1

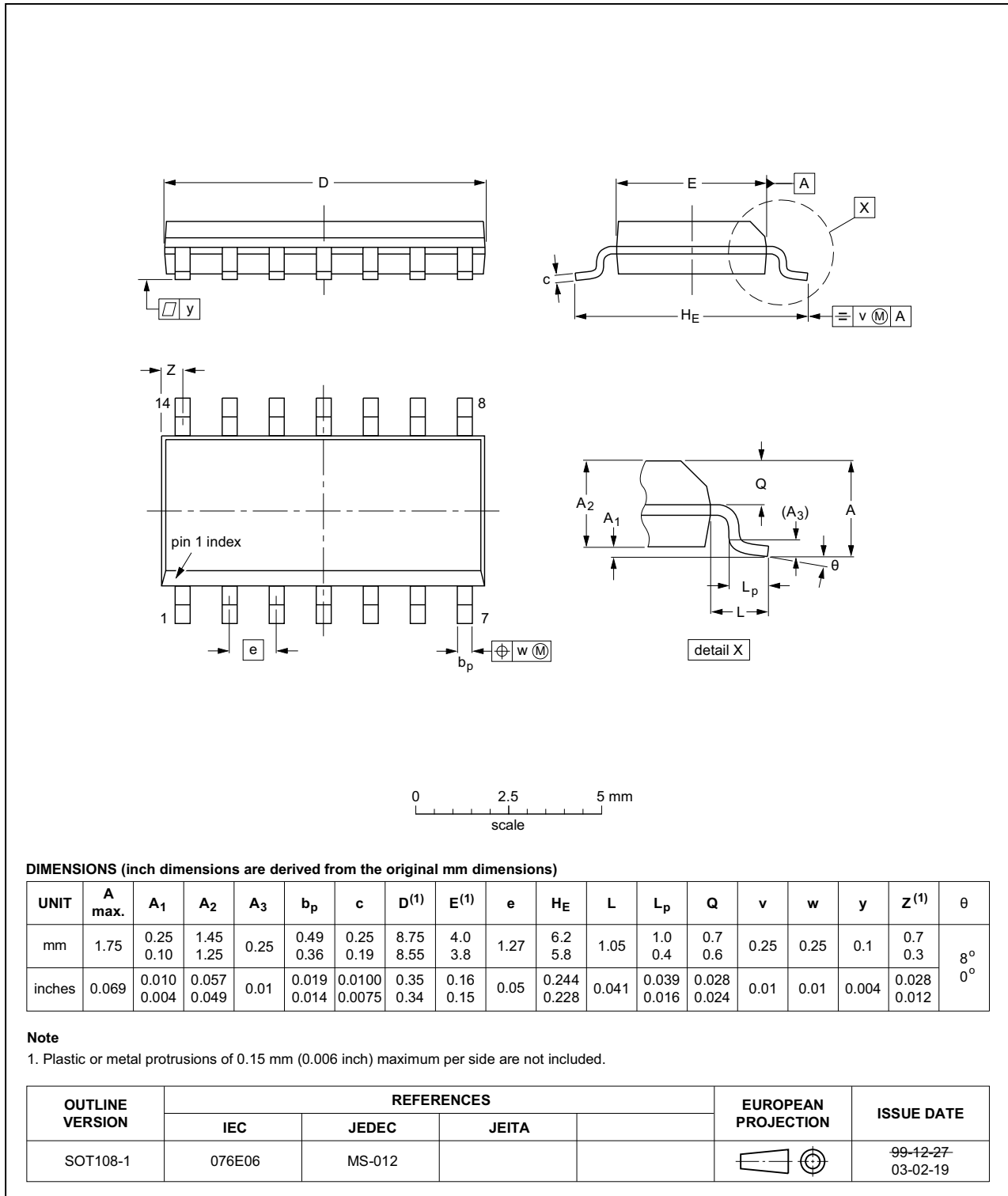


Fig 14. Package outline SOT108-1 (SO14)

TSSOP14: plastic thin shrink small outline package; 14 leads; body width 4.4 mm

SOT402-1

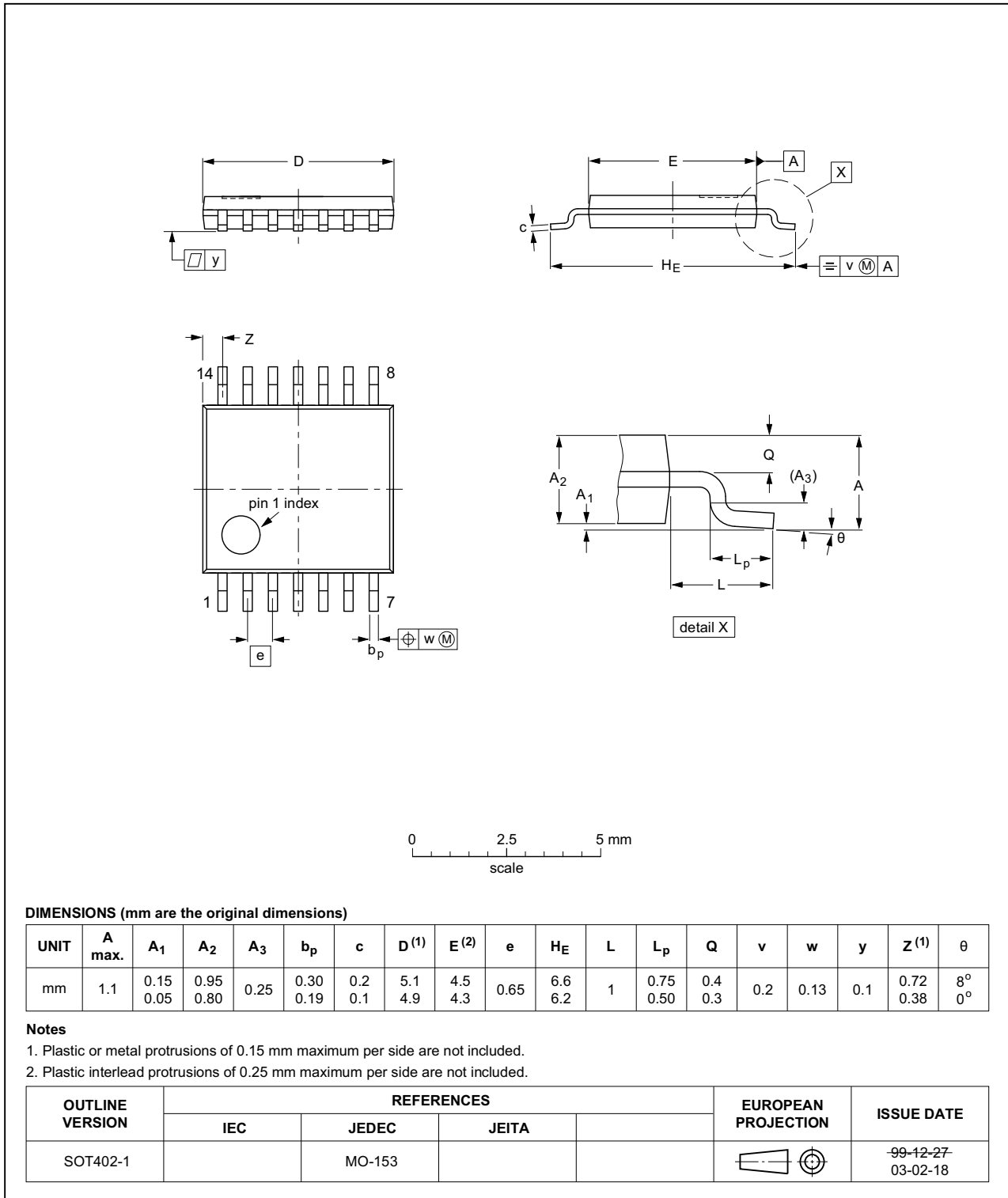


Fig 15. Package outline SOT402-1 (TSSOP14)

## 14. Abbreviations

Table 9. Abbreviations

Acronym	Description
HBM	Human Body Model
ESD	ElectroStatic Discharge
MM	Machine Model
MIL	Military

## 15. Revision history

Table 10. Revision history

Document ID	Release date	Data sheet status	Change notice	Supersedes
HEF4069UB_Q100 v.2	20140909	Product data sheet	-	HEF4069UB_Q100 v.1
Modifications:	• <a href="#">Section 2</a> : ESD protection: MIL-STD-833 changed to MIL-STD883			
HEF4069UB_Q100 v.1	20130228	Product data sheet	-	-

## 16. Legal information

### 16.1 Data sheet status

Document status <sup>[1][2]</sup>	Product status <sup>[3]</sup>	Definition
Objective [short] data sheet	Development	This document contains data from the objective specification for product development.
Preliminary [short] data sheet	Qualification	This document contains data from the preliminary specification.
Product [short] data sheet	Production	This document contains the product specification.

[1] Please consult the most recently issued document before initiating or completing a design.

[2] The term 'short data sheet' is explained in section "Definitions".

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